COMP 322: Fundamentals of Parallel Programming

Lecture 35: Partitioned Global Address Space (PGAS) languages

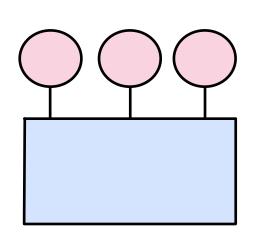
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(Ack: many slides are courtesy of John Mellor-Crummey)

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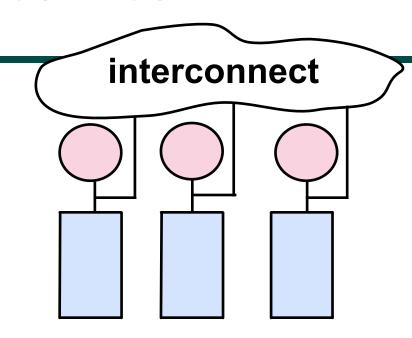
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Parallel Architectures







Distributed Memory

Programming Models

Habanero-Java Java Threads Cilk OpenMP Pthreads

Process/Thread

Memory

MPI Map-Reduce UPC CAF

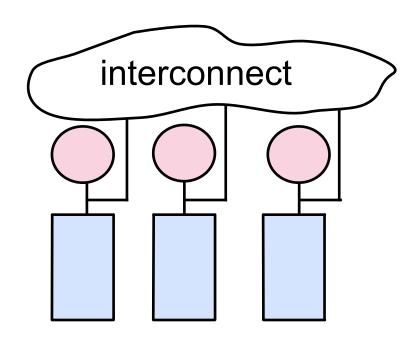


Performance and Programmability Concerns

Data movement and synchronization are expensive

To minimize overheads

- Co-locate data with processes
- Aggregate multiple accesses to remote data
- Overlap communication with computation
- ⇒ Significant programmability challenges with addressing these overheads in a shared-nothing programming model like MPI



Distributed Memory

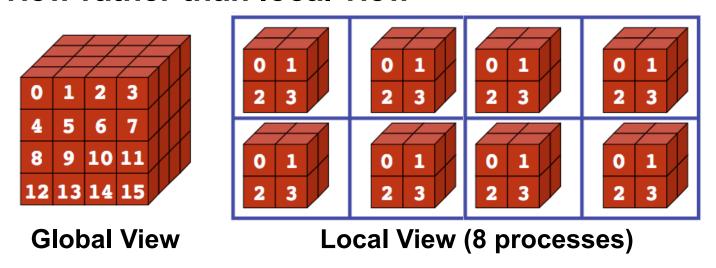


Partitioned Global Address Space Languages

- Global address space
 - -one-sided communication (GET/PUT) simpler than msg passing
- Programmer has control over performance-critical factors
 - —<u>data distribution</u> and locality control
- lacking in thread-based models

- —computation partitioning
- —communication placement

- HJ places help with locality control but not data distribution
- Data movement and synchronization as language primitives
 - —amenable to compiler-based communication optimization
- Global view rather than local view



Partitioned Global Address Space (PGAS) Languages

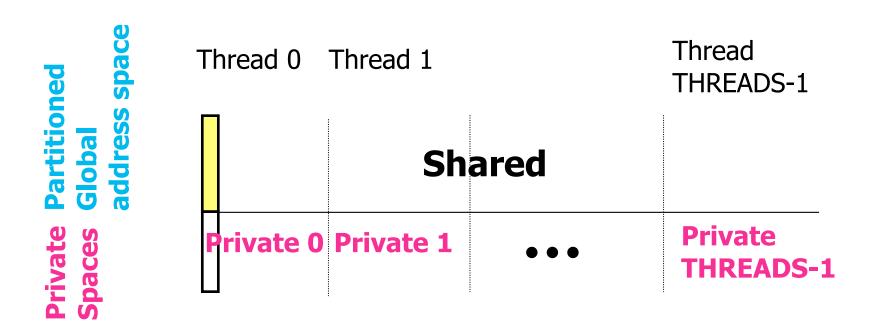
- Unified Parallel C (extension of C)
- Coarray Fortran (extension of Fortran)
- Titanium (extension of early version of Java)

- Related efforts: newer languages developed since 2003 as part of the DARPA High Productivity Computing Systems (HPCS) program
 - —IBM: X10 (starting point for Habanero-Java)
 - —Cray: Chapel
 - —Oracle/Sun: Fortress



Data Distributions

- Motivation for distributions: partitioning and mapping arrays elements to processors
- In HJlib, distributions are used to map computations to places for affinity
- For Unified Parallel C (UPC), distributions map data onto distributed-memory parallel machines (Thread = Place)



Like shared vs. private/local data in HJ, except now each datum also has an "affinity" with a specific thread/place



Unified Parallel C (UPC)

- An explicit parallel extension of ISO C
 - —a few extra keywords
 - shared, MYTHREAD, THREADS, upc forall
- Language features
 - —partitioned global address space for shared data
 - part of shared data co-located with each thread
 - —threads created at application launch
 - each bound to a CPU
 - each has some private data
 - —a memory model
 - defines semantics of interleaved accesses to shared data
 - —synchronization primitives
 - barriers
 - locks
 - load/store



UPC Execution Model

- Multiple threads working independently in a SPMD fashion
 - —MYTHREAD specifies thread index (0..THREADS-1)
 - Like MPI processes and ranks
 - —# threads specified at compile-time or program launch
- Partitioned Global Address Space (different from MPI)

ned s space	Thread 0 Thread 1			Thread THREADS-1
Partitioned Global address spa			Shared	
Private Spaces	Private 0	Private 1	•••	Private THREADS-1

- Threads synchronize as necessary using
 - —synchronization primitives
 - —shared variables



Shared and Private Data

- Static and dynamic memory allocation of each type of data
- Shared objects placed in memory based on affinity
 - —shared scalars have affinity to thread 0
 - here, a scalar means a singleton instance of any type
 - by default, elements of shared arrays are allocated "round robin" among memory modules co-located with each thread (cyclic distribution)



A One-dimensional Shared Array

Consider the following data layout directive

```
shared int y[2 * THREADS + 1];
```

For THREADS = 3, we get the following cyclic layout

Thread 0

y[0]

y[3]

y[6]

Thread 1

y[1]

y[4]

Thread 2

y[2]

y[5]



A Multi-dimensional Shared Array

```
shared int A[4][THREADS];
```

For THREADS = 3, we get the following cyclic layout

Thread	0
--------	---

A[0][0]
A[1][0]
A[2][0]
A[3][0]

Thread 1

A[0][1]
A[1][1]
A[2][1]
A[3][1]

Thread 2

A[0][2]
A[1][2]
A[2][2]
A[3][2]



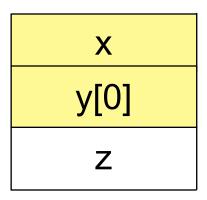
Shared and Private Data

Consider the following data layout directives

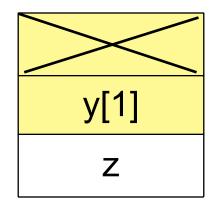
```
shared int x; // x has affinity to thread 0
shared int y[THREADS];
int z; // private
```

For THREADS = 3, we get the following layout

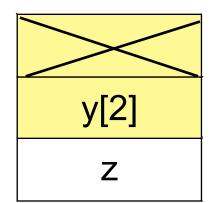
Thread 0



Thread 1



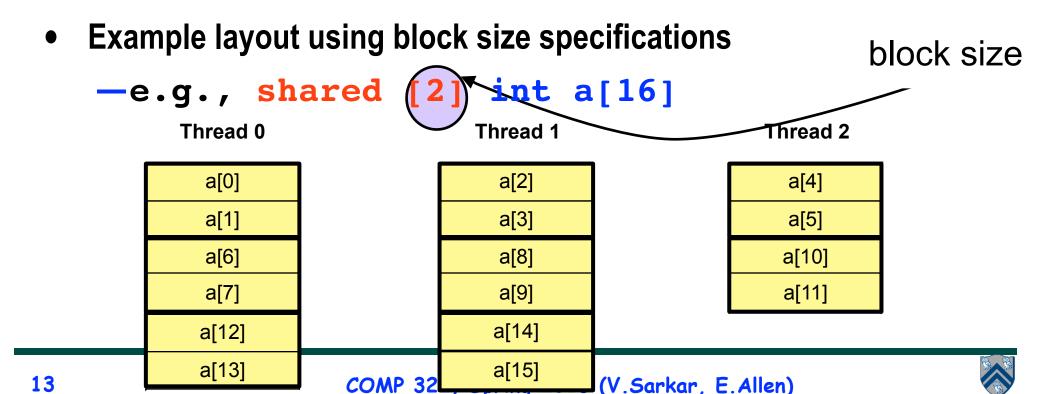
Thread 2





Controlling the Layout of Shared Arrays

- Can specify a blocking factor for shared arrays to obtain blockcyclic distributions
 - —default block size is 1 element ⇒ cyclic distribution
- Shared arrays are distributed on a block per thread basis, round robin allocation of block size chunks



Blocking Multi-dimensional Data

Consider the data declaration

```
-shared [3] int A[4][THREADS];
```

When THREADS = 4, this results in the following data layout

Thread 0

A[0][0]
A[0][1]
A[0][2]
A[3][0]
A[3][1]
A[3][2]

Thread 1

A[0][3] A[1][0] A[1][1] A[3][3] Thread 2

A[1][2] A[1][3] A[2][0] Thread 3

A[2][1] A[2][2] A[2][3]

The mapping is not pretty for most blocking factors



Shared Space

A Simple UPC Program: Vector Addition

```
//vect add.c
                                              Thread 0 Thread 1
#include <upc relaxed.h>
#define N 100*THREADS
                                  Iteration #:
shared int v1[N], v2[N], v1plusv2[N];
                                                v1[0]
                                                          v1[1]
                                                v1[2]
                                                         v1[3]
void main() {
  int i;
  for(i=0; i<N; i++)
                                                v2[0]
                                                          v2[1]
     if (MYTHREAD == i % THREADS)
                                                v2[2]
                                                          v2[3]
        v1plusv2[i]=v1[i]+v2[i];
                                              v1plusv2[0]
                                                       v1plusv2[1]
                                              v1plusv2[2]
                                                       v1plusv2[3]
```

Each thread executes each iteration to check if it has work



Shared Space

A More Efficient Vector Addition

```
Thread 0 Thread 1
//vect add.c
                                       Iteration #:
#include <upc relaxed.h>
#define N 100*THREADS
                                                     v1[0]
                                                               v1[1]
                                                              v1[3]
                                                     v1[2]
shared int v1[N], v2[N], v1plusv2[N];
                                                     v2[0]
                                                               v2[1]
void main() {
                                                     v2[2]
                                                               v2[3]
  int i;
  for(i = MYTHREAD; i < N; i += THREADS)</pre>
                                                   v1plusv2[0]
                                                            v1plusv2[1]
    v1plusv2[i]=v1[i]+v2[i];
                                                   v1plusv2[2]
                                                            v1plusv2[3]
```

Each thread executes only its own iterations



Worksharing with upc_forall

- Distributes independent iterations across threads
- Simple C-like syntax and semantics

```
-upc_forall(init; test; loop; affinity)
```

- Affinity is used to enable locality control
 - —usually, map iteration to thread where the iteration's data resides
- Affinity can be
 - —an integer expression, or a
 - —reference to (address of) a shared object



Work Sharing + Affinity with upc forall

Example 1: explicit affinity using shared references

```
shared int a[100],b[100], c[100];
int i;
upc_forall (i=0; i<100; i++; &a[i])
  // Execute iteration i at a[i]'s thread/place
  a[i] = b[i] * c[i];</pre>
```

• Example 2: implicit affinity with integer expressions

```
shared int a[100],b[100], c[100];
int i;
upc_forall (i=0; i<100; i++; i)
  // Execute iteration i at place i%THREADS
a[i] = b[i] * c[i];</pre>
```

Both yield a round-robin distribution of iterations



Shared Space

Vector Addition Using upc_forall

thread affinity for work: have thread i execute iteration i Thread 0 Thread 1 //vect add.c #include <upc relaxed.h> **Iteration #:** #define N 100*THREADS v1[0] v1[1] v1[3] v1[2] shared int v1[N], v2[N], v1pl\usv2[N]; v2[0] v2[1] void main() v2[2] v2[3] int i; upc forall(i = 0; i < N; i++;(i)) v1plusv2[0] v1plusv2[1] v1plusv2[i]=v1[i]+v2[i]; v1plusv2[3] v1plusv2[2]

Each thread executes subset of global iteration space as directed by the affinity clause

Work Sharing + Affinity with upc forall

Example 3: implicit affinity by chunks

```
shared [25] int a[100],b[100], c[100];
int i;
upc_forall (i=0; i<100; i++; (i*THREADS)/100)
    a[i] = b[i-1] * c[i+1];</pre>
```

Assuming 4 threads, the following results

i	i*THREADS	i*THREADS/100
024	096	0
2549	100196	1
5074	200296	2
7599	300396	3



Matrix-Vector Multiply (Default Distribution)

```
// vect mat mult.c
#include <upc relaxed.h>
shared int a[THREADS][THREADS];
shared int b[THREADS], c[THREADS];
void main (void) {
      int i, j;
      upc_forall(i = 0; i < THREADS; i++; i) {</pre>
             c[i] = 0;
             for (j=0; j < THREADS; j++)
                   c[i] += a[i][j]*b[j];
             Th. 0
                                         Th. 0
             Th. 1
                                         Th. 1
             Th. 2
                                         Th. 2
                                          В
```

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Matrix-Vector Multiply (Better Distribution)

```
// vect mat mult.c
#include <upc relaxed.h>
shared [THREADS] int a[THREADS][THREADS];
shared int b[THREADS], c[THREADS];
void main (void) {
      int i, j;
      upc forall( i = 0 ; i < THREADS ; i++; i) {</pre>
             c[i] = 0;
             for (j=0; j< THREADS; j++)
                   c[i] += a[i][j]*b[j];
                                         Th. 0
              Th. 0
                          Thread 0
              Th. 1
                          Thread 1
                                         Th. 1
              Th. 2
                          Thread 2
                                          В
```

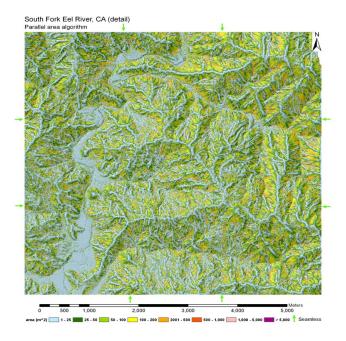
Synchronization

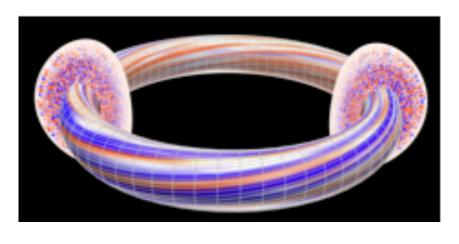
- Barriers (blocking)
 - —upc_barrier
 - like "next" operation in HJ
- Split-phase barriers (non-blocking)
 - —upc_notify
 - like explicit (non-blocking) signal on an HJ phaser
 - —upc_wait
 - upc_wait is like explicit wait on an HJ phaser
- Lock primitives
 - —void upc_lock(upc_lock_t *l)
 - —int upc_lock_attempt(upc_lock_t *I) // like trylock()
 - —void upc_unlock(upc_lock_t *I)

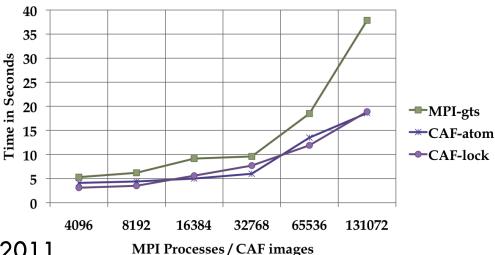


Application Work in PGAS

- Network simulator in UPC (Steve Hofmeyr)
- Barnes-Hut in UPC (Marc Snir et al)
- Landscape analysis
 - —"Contributing Area Estimation" in UPC (Brian Kazian, UCB)
- Gyrokinetic Tokamak Simulation Shifter code in CoArray Fortran (CAF)
 - —Preissl, Wichmann, Long, Shalf, Ethier, Koniges (LBNL, Cray, PPPL)







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