COMP 322: Fundamentals of Parallel Programming

Lecture 2: Async-Finish Parallel Programming and Computation Graphs

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https://wiki.rice.edu/confluence/display/PARPROG/COMP322



Acknowledgments for Today's Lecture

- Cilk lectures, http://supertech.csail.mit.edu/cilk/
- PrimeSieve.java example
 - http://introcs.cs.princeton.edu/java/14array/PrimeSieve.java.html



Goals for Today's Lecture

- Discussion of Async and Finish constructs
- Understanding when two statements can run in parallel
- Understanding limits to ideal parallelism (critical path length)



Async and Finish Statements for Task Creation and Termination (Recap)

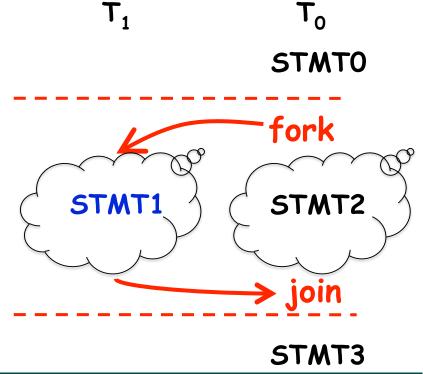
async S

 Creates a new child task that executes statement S

finish S

 Execute S, but wait until all asyncs in S's scope have terminated.

```
// T<sub>0</sub>(Parent task)
STMT0;
finish {    //Begin finish
    async {
        STMT1; //T<sub>1</sub>(Child task)
    }
    STMT2; //Continue in T<sub>0</sub>
        //Wait for T<sub>1</sub>
}
STMT3; //Continue in T<sub>0</sub>
```





Some Properties of Async & Finish constructs

- 1. Scope of async/finish can be any arbitrary statement
 - async/finish constructs can be arbitrarily nested e.g.,
 - finish { async S1; finish { async S2; S3; } S4; } S5;
- 2. A method may return before all its async's have terminated
 - Enclose method body in a finish if you don't want this to happen
 - main() method is enclosed in an implicit finish e.g.,
 - main() { foo();} void foo() {async S1; S2; return;}
- 3. Each dynamic async task will have a unique Immediately Enclosing Finish (IEF) at runtime
- 4. Async/finish constructs cannot "deadlock"
 - Cannot have a situation where both task A waits for task B to finish,
 and task B waits for task A to finish
- 5. Async tasks can read/write shared data via objects and arrays
 - Local variables have special restrictions (next slide)



Local Variables

Three rules for accessing local variables across tasks in HJ:

1) An async may read the value of any final outer local var final int i1 = 1; async { ... = i1; /* i1=1 */ }

2) An async may read the value of any non-final outer local var (copied on entry to async like method parameters)

```
int i2 = 2; // i2=2 is copied on entry to the async
async { ... = i2; /* i2=2*/}
i2 = 3; // This assignment is not seen by the above async
```

3) An async is not permitted to modify an outer local var

```
int[] A; async { A = ...; /*ERROR*/ A[i] = ...; /*OK*/ }
```



Converting sequential Java programs to parallel Async-Finish HJ programs

One possible approach:

- 1. Create "ideal" parallel version
- Insert async's at all points where parallelism can logically be exploited
- Insert finish's to ensure that the parallel version produces the same results as the sequential version
- 2. Transform ideal parallelism to useful parallelism
- Merge or remove async's to amortize overhead
- Replace finish by more efficient synchronization constructs (to be covered later in course)



Java Example: Sieve of Eratosthenes

```
1. // initially assume all integers are prime
2.
    boolean[] isPrime = new boolean[N + 1];
    for (int i = 2; i \le N; i++) isPrime[i] = true;
    // mark non-primes <= N using Sieve of Eratosthenes</pre>
5.
    for (int i = 2; i*i \le N; i++)
6.
      // if i is prime, then mark multiples of i as nonprime
7.
     if (isPrime[i])
8.
          for (int j = i; i*j \le N; j++)
9.
              isPrime[i*j] = false;
10. // count primes
11. int primes = 0;
12. for (int i = 2; i \le N; i++) if (isPrime[i]) primes++;
```

How should we parallelize the sieve computation in lines 5-9?



Ideal Parallelization of Sieve Computation

```
1. // initially assume all integers are prime
2.
    boolean[] isPrime = new boolean[N + 1];
    for (int i = 2; i \le N; i++) isPrime[i] = true;
    // mark non-primes <= N using Sieve of Eratosthenes</pre>
5.
    for (int i = 2; i*i \le N; i++)
6.
      // if i is prime, then mark multiples of i as nonprime
7.
     if (isPrime[i])
8.
          \underline{\text{finish}} for (int j = i; i*j <= N; j++)
              async isPrime[i*j] = false;
9.
10. // count primes
11. int primes = 0;
12. for (int i = 2; i <= N; i++) if (isPrime[i]) primes++;
```

Is this approach correct? Is it efficient?



Which statements can potentially be executed in parallel with each other?

```
Computation Graph
    finish { // F1
2.
    async A1;
3.
        finish { // F2
                           spawn
                                                 join
4.
       async A3;
  async A4;
  } // F2
                               F2-start
                                         F2-end
                       F1-start
                                                        F1-end
7. S5;
8. } // F1
```



Computation Graphs for HJ Programs

- A Computation Graph (CG) captures the dynamic execution of an HJ program, for a specific input
- · CG nodes are "steps" in the program's execution
 - A step is a sequential subcomputation without any async, begin-finish and end-finish operations
- CG edges represent ordering constraints
 - "Continue" edges define sequencing of steps within a task
 - "Spawn" edges connect parent tasks to child async tasks
 - "Join" edges connect the end of each async task to its IEF's end-finish operations



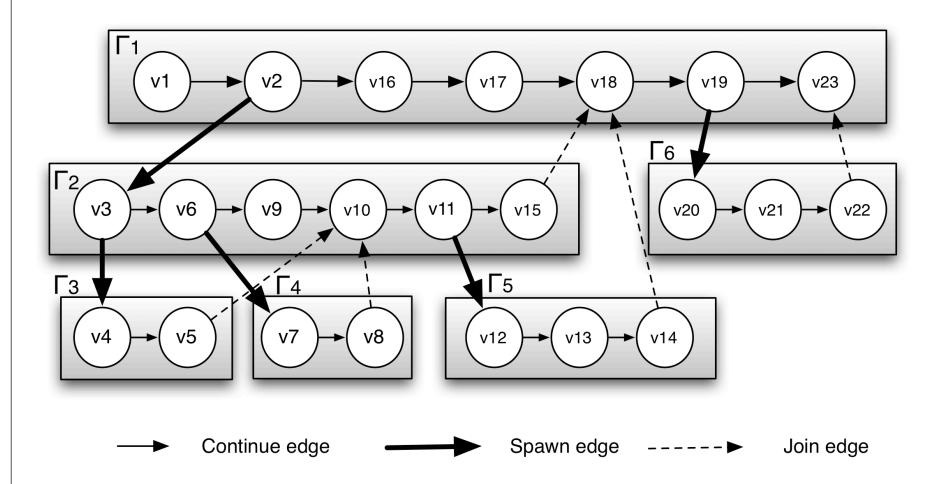
Example HJ Program with statements v1 ... v23

```
// Task T1
v1; v2;
finish {
 async {
   // Task T2
   v3:
   finish {
     async { v4; v5; } // Task T3
     v6:
     async { v7; v8; } // Task T4
     v9:
   } // finish
   v10; v11;
```

```
// Task T2 (contd)
   async { v12; v13;
           v14; } // Task T5
   v15:
 } // end of task T2
 v16; v17; // back in Task T1
} // finish
v18; v19;
finish {
 async {
   // Task T6
   v20; v21; v22; }
v23:
```



Computation Graph for previous HJ Example



Example: Step v16 can potentially execute in parallel with steps v3 ... v15



Complexity Measures for Computation Graphs

Define

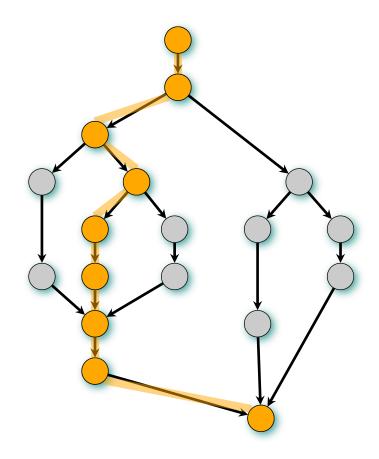
- TIME(N) = execution time of node N
- WORK(G) = sum of TIME(N), for all nodes N in CG G
 - -WORK(G) is the total work to be performed in G
- CPL(G) = length of a longest path in CG G, when adding up execution times of all nodes in the path
 - —Such paths are called critical paths
 - -CPL(G) is the length of these paths (critical path length)



Ideal Speedup

Define ideal speedup of Computation G Graph as the ratio, WORK(G)/CPL(G)

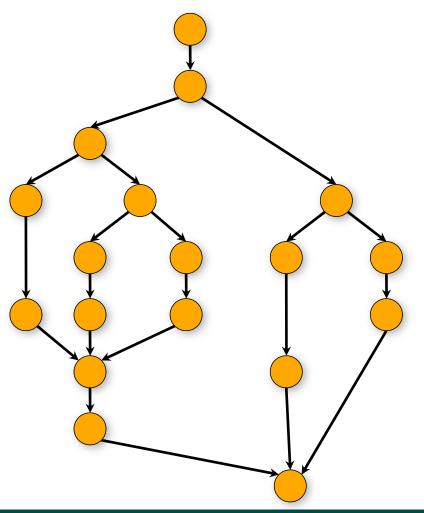
Ideal Speedup is independent of the number of processors that the program executes on, and only depends on the computation graph





Example

Assume time(N) = 1 for all nodes in this graph

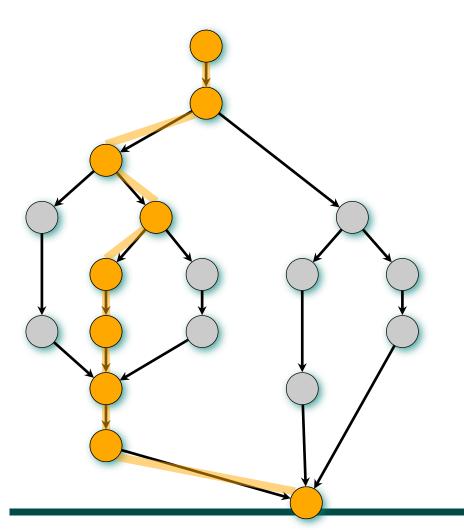


WORK(G) = 18



Example (contd)

Assume time(N) = 1 for all nodes in this graph



$$CPL(G) = 9$$

Ideal speedup
= WORK(G)/CPL(G)

= 2



Homework 1 Reminder

- · Written assignment, due by Friday, Jan 13th
- Submit a softcopy of your solution in Word, PDF, or plain text format
 - —Try and use turn-in script for submission, if possible
 - -Otherwise, email your homework to comp322-staff at mailman.rice.edu
- See course web site for penalties for late submissions
 - —Send me email if you have an extenuating circumstance for delay

