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# COMP 322: Fundamentals of Parallel Programming

## Lecture 7: Memory Models (contd), Futures --- Tasks with Return Values

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# Goals for Today's Lecture

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- Code Transformations and Memory Consistency Models
- Futures --- Tasks with Return Values

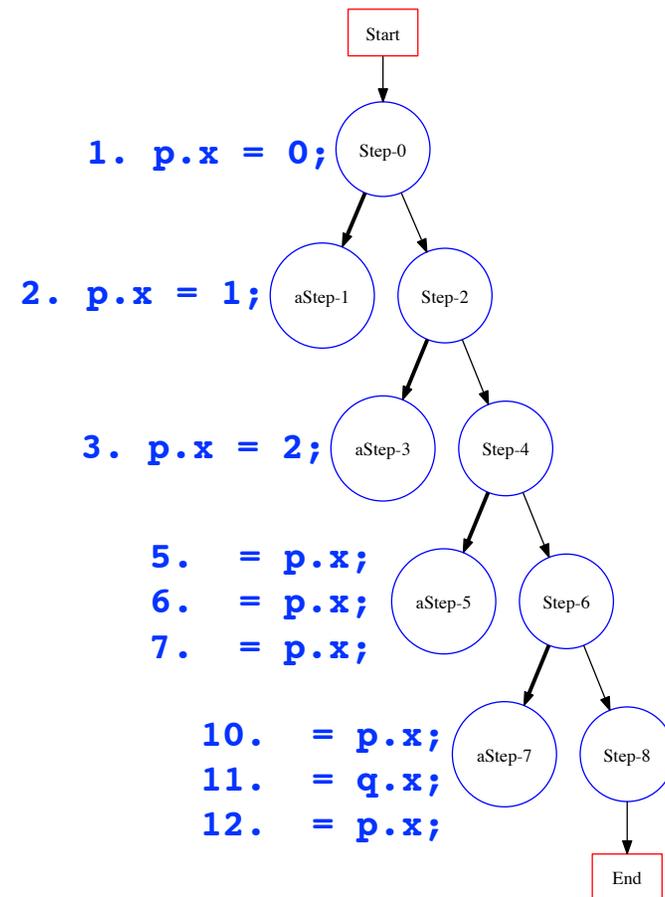


# Memory Consistency Models (Recap)

- A memory consistency model, or memory model, is the part of a programming language specification that defines what write values a read may see in the presence of data races.

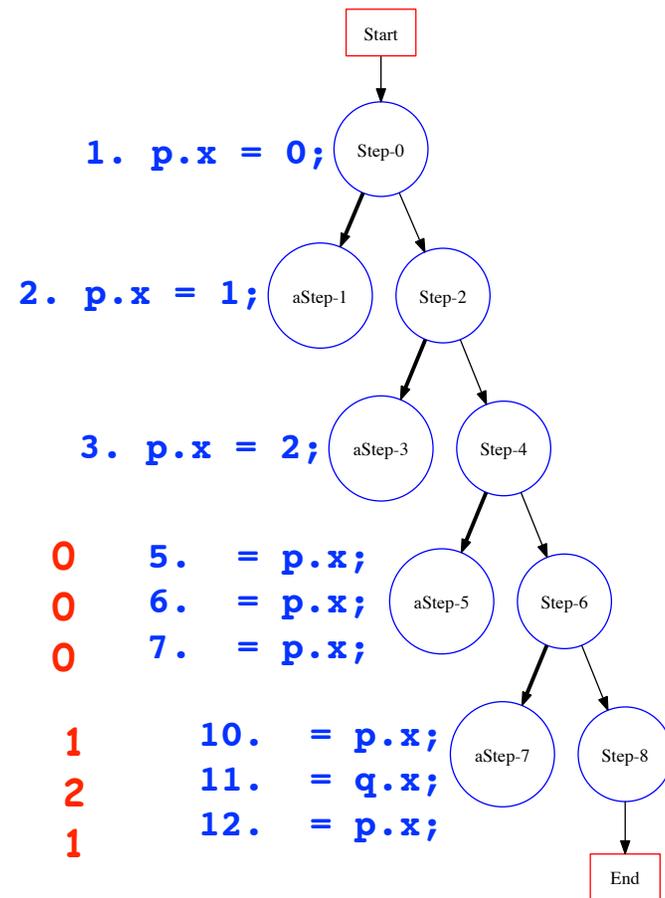
## Example HJ program:

```
1. p.x = 0; q = p;
2. async p.x = 1; // Task T1
3. async p.x = 2; // Task T2
4. async { // Task T3
5.   System.out.println("First read = " + p.x);
6.   System.out.println("Second read = " + p.x);
7.   System.out.println("Third read = " + p.x)
8. }
9. async { // Task T4
10.  System.out.println("First read = " + p.x);
11.  System.out.println("Second read = " + q.x);
12.  System.out.println("Third read = " + p.x);
13. }
```



# Memory Consistency Models (Recap)

- A memory consistency model, or memory model, is the part of a programming language specification that defines what write values a read may see in the presence of data races.



The following reads are prohibited by Sequential Consistency (SC), but permitted by the Java Memory Model (JMM) and Habanero-Java Memory Model (HJMM)

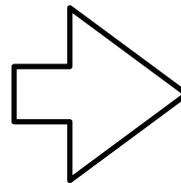


# Semantics-Preserving Code Transformations in Sequential Programs

- A Code Transformation is said to be semantics-preserving if the transformed program,  $P'$ , exhibits the same Input-Output behavior as the original program,  $P$
- For sequential programs, many local transformations are guaranteed to be semantics-preserving regardless of the context
  - e.g., replacing the second access of an object field or array element by a local variable containing the result of the first access, if there are no possible updates between the two accesses

$P$

```
1. static void foo(T p, T q) {
2.     System.out.println(p.x);
3.     System.out.println(q.x);
4.     System.out.println(p.x);
5. }
```



$P'$

```
1. static void foo(T p, T q) {
2.     int xLocal = p.x
3.     System.out.println(xLocal);
4.     System.out.println(q.x);
5.     System.out.println(xLocal);
6. }
```



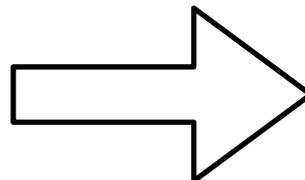
# Semantics-Preserving Code Transformations in Parallel Programs

- **Question:** What should we expect if we perform a Code Transformation on a sequential region of a parallel program, if the transformation is known to be semantics-preserving for sequential programs?
- **Answer:** The transformation should be semantics-preserving for the parallel program if there are no data races. Otherwise, it depends on the memory model!

**P**

```
1. p.x = 0; q = p;
2. async p.x = 1;
3. async p.x = 2;
4. async foo(p, p);
5. async foo(p, q);
6. . . .
7. static void foo(T p, T q) {
8.     System.out.println(p.x);
9.     System.out.println(q.x);
10.    System.out.println(p.x);
11. }
```

**Is this a legal transformation?**



**It may result in the following output:**

**0 0 0**  
**1 2 1**

**P'**

```
1. p.x = 0; q = p;
2. async p.x = 1;
3. async p.x = 2;
4. async foo(p, p);
5. async foo(p, q);
6. . . .
7. static void foo(T p, T q) {
8.     int xLocal = p.x
9.     System.out.println(xLocal);
10.    System.out.println(q.x);
11.    System.out.println(xLocal);
12. }
```

**==> Code transformation is legal for JMM & HJMM, but not for SC !**



# Summary of Memory Model Discussion

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- Memory model specifies rules for what write values can be seen by reads in the presence of data races
  - In the absence of data races, program semantics specifies exactly one write for each read
- A local code transformation performed on a sequential code region may be semantics-preserving for sequential programs, but not necessarily for parallel programs
  - Stronger memory models (e.g., SC) are more restrictive about permissible read sets than weaker memory models (e.g., JMM, HJMM), and thus more restrictive about allowing transformations
- Different memory models are appropriate for different levels of the software stack
  - e.g., SC at the OS/HW level, JMM at the thread level, HJMM at the task level

HJMM

JMM

SC



# Goals for Today's Lecture

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- Code Transformations and Memory Consistency Models
- Futures --- Tasks with Return Values



# Extending Async Tasks with Return Values

- Example Scenario in PseudoCode

```
1. // Parent task creates child async task
2. container = async<int> { return computeSum(X, low, mid); };
3. . . .
4. // Later, parent examines the return value
5. int sum = container.get();
```

- Two key issues to be addressed:

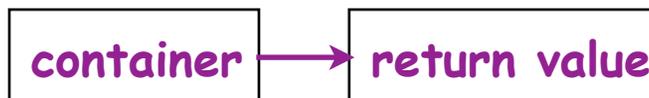
- 1) Distinction between container and value in container
- 2) Synchronization to avoid race condition in container accesses

## Parent Task

```
container = async {...}
. . .
container.get()
```

## Child Task

```
computeSum(...)
return ...
```



# HJ Futures: Tasks with Return Values

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`async<T> { <Stmt-Block> }`

- Creates a new child task that executes `Stmt-Block`, which must terminate with a `return` statement returning a value of type `T`
- Async expression returns a reference to a container of type `future<T>`
- Values of type `future<T>` can only be assigned to final variables

`Expr.get()`

- Evaluates `Expr`, and blocks if `Expr`'s value is unavailable
- `Expr` must be of type `future<T>`
- Return value from `Expr.get()` will then be `T`
- Unlike `finish` which waits for all tasks in the `finish` scope, a `get()` operation only waits for the specified `async` expression



# Example: Two-way Parallel Array Sum using Future Tasks

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```
1. // Parent Task T1 (main program)
2. // Compute sum1 (lower half) and sum2 (upper half) in parallel
3. final future<int> sum1 = async<int> { // Future Task T2
4.     int sum = 0;
5.     for(int i=0 ; i < X.length/2 ; i++) sum += X[i];
6.     return sum;
7. }; //NOTE: semicolon needed to terminate assignment to sum1
8. final future<int> sum2 = async<int> { // Future Task T3
9.     int sum = 0;
10.    for(int i=X.length/2 ; i < X.length ; i++) sum += X[i];
11.    return sum;
12. }; //NOTE: semicolon needed to terminate assignment to sum2
13. //Task T1 waits for Tasks T2 and T3 to complete
14. int total = sum1.get() + sum2.get();
```

Why are these semicolons needed?



# Future Task Declarations and Uses

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- Variable of type `future<T>` is a reference to a future object
  - Container for return value of `T` from future task
  - The reference to the container is also known as a “handle”
- Two operations that can be performed on variable `V1` of type `future<T1>` (assume that type `T2` is a subtype of type `T1`):
  - Assignment: `V1` can be assigned value of type `future<T2>`
  - Blocking read: `V1.get()` waits until the future task referred to by `V1` has completed, and then propagates the return value
- Future task body must start with a type declaration, `async<T1>`, where `T1` is the type of the task's return value
- Future task body must consist of a statement block enclosed in `{ }` braces, terminating with a return statement



# Comparison of Future Task and Regular Async Versions of Two-Way Array Sum

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- Future task version initializes two references to future objects, `sum1` and `sum2`, and both are declared as `final`
- No `finish` construct needed in this example
  - Instead parent task waits for child tasks by performing `sum1.get()` and `sum2.get()`
- **Guaranteed absence of race conditions in Future Task example**
  - No race on `sum` because it is a local variable in tasks T2 and T3
  - No race on future variables, `sum1` and `sum2`, because of blocking-read semantics



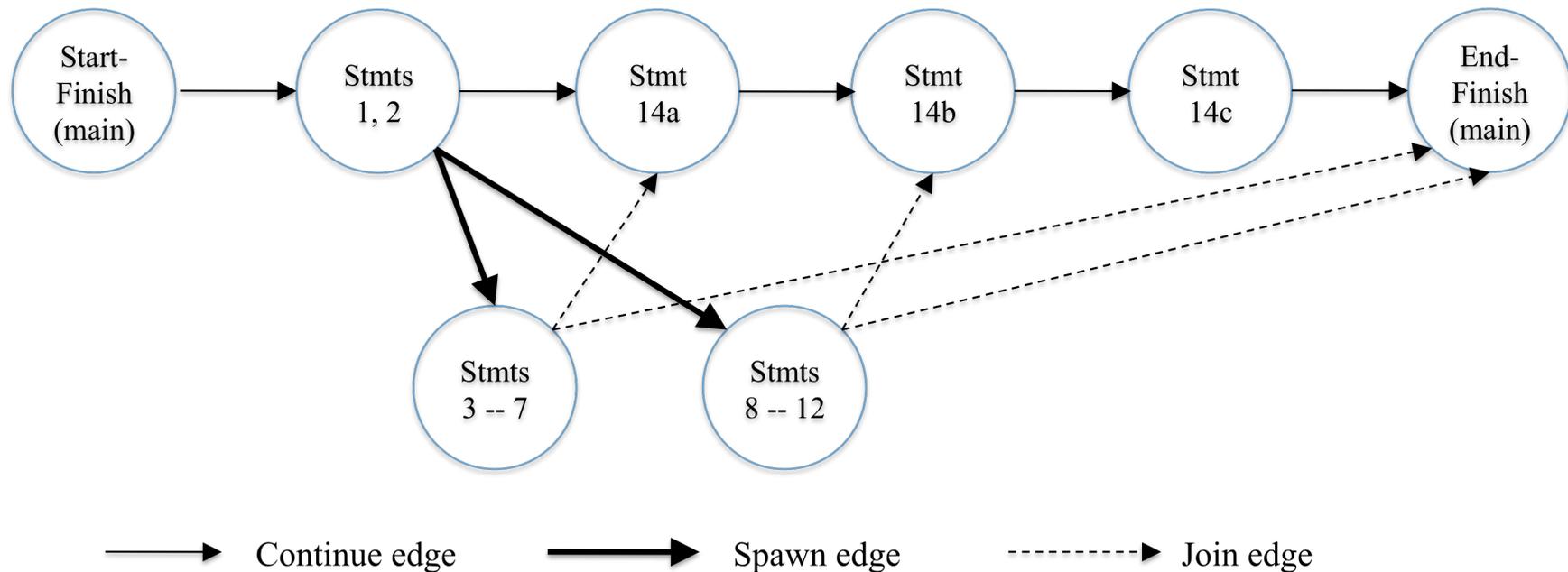
# Computation Graph Extensions for Future Tasks

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- Since a `get()` is a blocking operation, it must occur on boundaries of *CG* nodes/steps
  - May require splitting a statement into sub-statements e.g.,
    - 14: `int sum = sum1.get() + sum2.get();`  
can be split into three sub-statements
      - 14a `int temp1 = sum1.get();`
      - 14b `int temp2 = sum2.get();`
      - 14c `int sum = temp1 + temp2;`
- Spawn edge connects parent task to child future task, as before
- Join edge connects end of future task to Immediately Enclosing Finish (IEF), as before
- Additional join edges are inserted from end of future task to each `get()` operation on future object



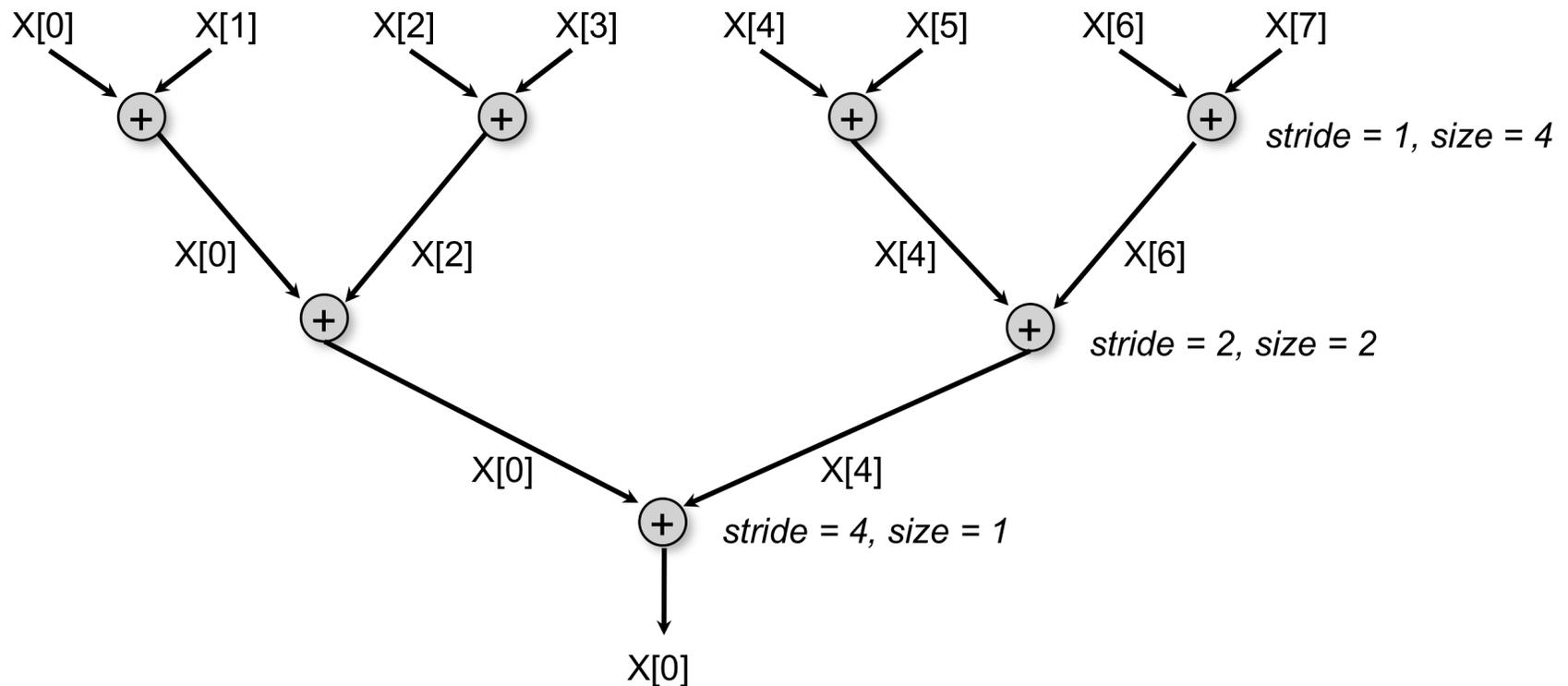
# Computation Graph for Two-way Parallel Array Sum using Future Tasks



**NOTE:** Generation of computation graphs and data race detection in current HJ implementation do not support futures as yet



# Reduction Tree Schema in ArraySum1 (Recap)



## Questions:

- How can we implement this schema using future tasks instead?
- Can we avoid overwriting elements of array X?



# Array Sum using Future Tasks (ArraySum2)

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## Recursive divide-and-conquer pattern

```
1.  static int computeSum(int[] X, int lo, int hi) {
2.      if ( lo > hi ) return 0;
3.      else if ( lo == hi ) return X[lo];
4.      else {
5.          int mid = (lo+hi)/2;
6.          final future<int> sum1 =
7.              async<int> { return computeSum(X, lo, mid); };
8.          final future<int> sum2 =
9.              async<int> { return computeSum(X, mid+1, hi); };
10.         // Parent now waits for the container values
11.         return sum1.get() + sum2.get();
12.     }
13. } // computeSum
14. int sum = computeSum(X, 0, X.length-1); // main program
```



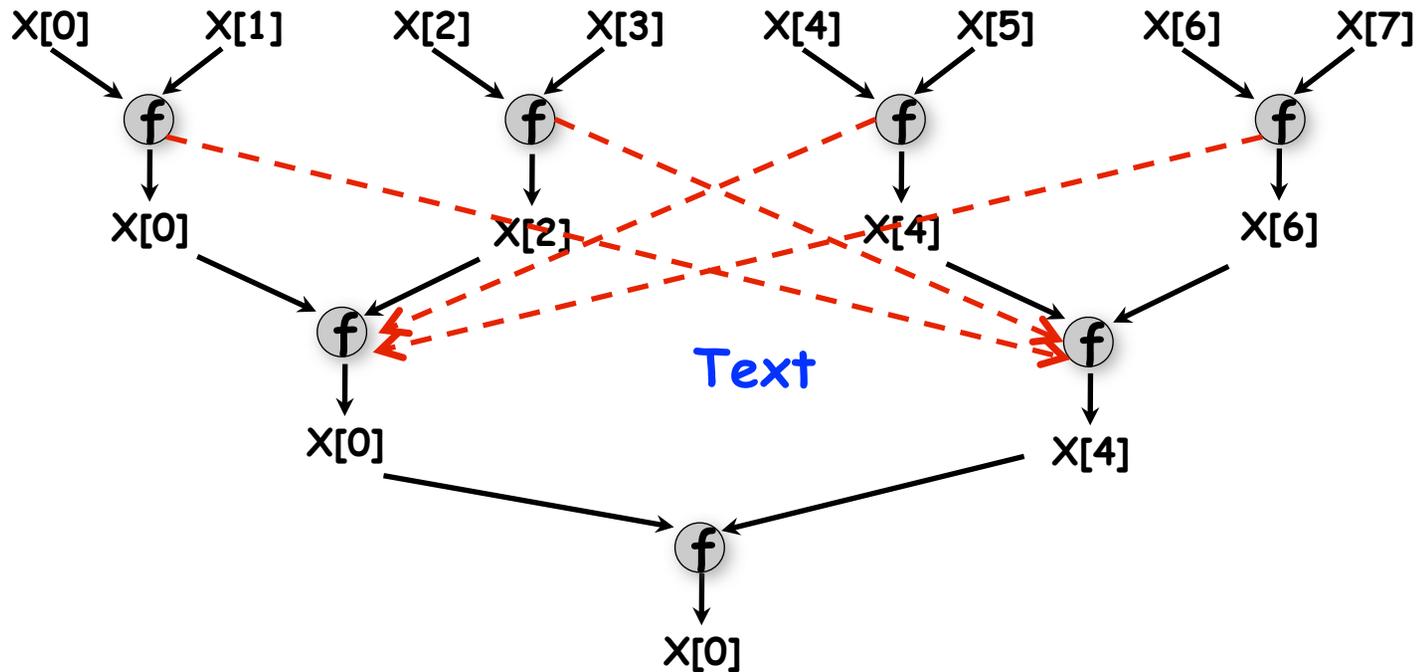
# Extension of ArraySum2 to reduce an arbitrary associative function, f

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```
1. static int reduce(int[] X, int lo, int hi) {
2.   if ( lo > hi ) return identity();
3.   else if ( lo == hi ) return X[lo];
4.   else {
5.     int mid = (lo+hi)/2;
6.     final future<int> sum1 =
7.       async<int> {return computeSum(X, lo, mid);};
8.     final future<int> sum2 =
9.       async<int> {return computeSum(X, mid+1, hi);};
10.    return f(sum1.get(), sum2.get());
11.  }
12. } // computeSum
13. int retVal = reduce(X, 0, X.length-1); // main program
```



# Extra dependences in ArraySum1 program (for-finish-for-async)



--- → Extra dependence edges due to finish-async stages  
(not present in ArraySum2 version with futures)

- Which of ArraySum1 or ArraySum2 will perform better if the time taken by the reduction operator depends on its inputs e.g., as in WordCount ?



# Why must Future References be declared as final?

```
static future<int> f1=null;
static future<int> f2=null;

void main(String[] args) {
    f1 = async<int> {return a1();};
    f2 = async<int> {return a2();};
}
```

```
int a1() { // Task T1
    while (f2 == null); // spin loop
    return f2.get(); //T1 waits for T2
}

int a2() { // Task T2
    while (f1 == null); // spin loop
    return f1.get(); //T2 waits for T1
}
```

**cyclic wait condition**

- Above situation cannot arise in HJ because f1 and f2 must be final
- Final declaration ensures that variable (handle) cannot be modified after initialization
- **WARNING:** such spin loops are an example of bad parallel programming practice in application code (they should only be used by expert systems programmers, and even then sparingly)
  - Their semantics depends on the memory model!



# Future Tasks with void Return Type

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- Key difference between regular async's and future tasks is that future tasks have a `future<T>` return value
- We can get an intermediate capability by setting `T=void` as shown
- Can be useful if a task needs to synchronize on a specific task (instead of finish), but doesn't need a future object to communicate a return value

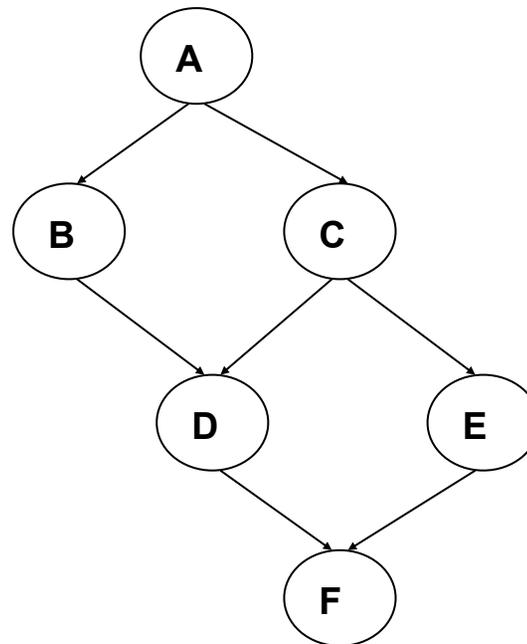
```
1. sum1 = 0; sum2 = 0; // Task T1
2. // Assume that sum1 & sum2 are fields
3. final future<void> a1 = async<void> {
4.     for (int i=0; i < X.length/2; i++)
5.         sum1 += X[i]; // Task T2
6. };
7. final future<void> a2 = async<void> {
8.     for (int i=X.length/2; i < X.length; i++)
9.         sum2 += X[i]; // Task T3
10. };
11. //Task T1 waits for Tasks T2 and T3
12. a1.get(); a2.get();
13. // Now fields sum1 and sum2 can be read
```



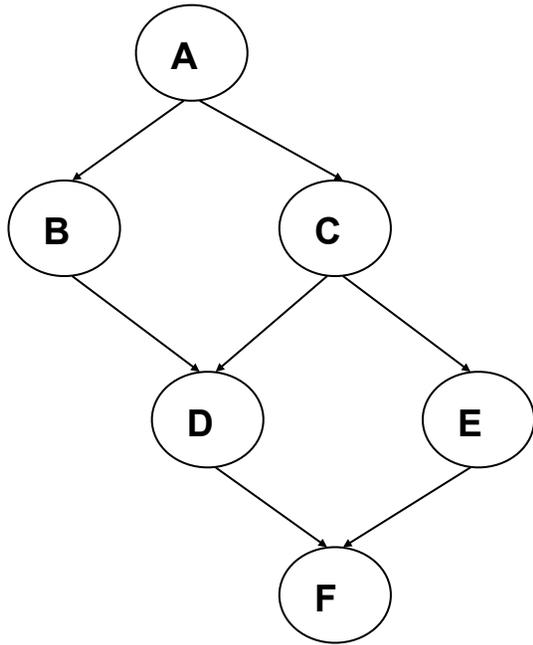
# Future Tasks can generate more general Computation Graphs than regular Async Tasks

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Can you write a finish-async HJ program that generates the following Computation Graph?



# Using Future Tasks to generate previous Computation Graph



Computation Graph

```
1. // NOTE: return statement is optional
2. // when return type is void
3. final future<void> A = async<void>
4.     { . . . };
5. final future<void> B = async<void>
6.     { A.get(); . . . };
7. final future<void> C = async<void>
8.     { A.get(); . . . };
9. final future<void> D = async<void>
10.    { B.get(); C.get(); . . . };
11. final future<void> E = async<void>
12.    { C.get(); . . . };
13. final future<void> F = async<void>
14.    { D.get(); E.get(); . . . }
```



# Homework 2 Reminder

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- Programming assignment, due Monday, Jan 30th
- Post questions on Piazza (preferred), or send email to comp322-staff at mailman.rice.edu
- You should plan to use turn-in script for HW2 submission
  - Contact teaching staff if you cannot access turn-in by following the instructions for Lab 1
- See course web site for penalties for late submissions

