Lecture 28: Introduction to the Message Passing Interface (MPI)
(Start of Module 3 on Distribution and Locality)

Mack Joyner and Zoran Budimlić
{mjoyner, zoran}@rice.edu

http://comp322.rice.edu
Worksheet #27: Characterizing Solutions to the Dining Philosophers Problem

For the five solutions studied in today’s lecture, indicate in the table below which of the following conditions are possible and why:

1. **Deadlock**: when all philosopher tasks are blocked (neither thinking nor eating)
2. **Livelock**: when all philosopher tasks are executing but ALL philosophers are starved (never get to eat)
3. **Starvation**: when one or more philosophers are starved (never get to eat)
4. **Non-Concurrency**: when more than one philosopher cannot eat at the same time, even when resources are available

<table>
<thead>
<tr>
<th></th>
<th>Deadlock</th>
<th>Livelock</th>
<th>Starvation</th>
<th>Non-concurrency</th>
</tr>
</thead>
<tbody>
<tr>
<td>Solution 1: synchronized</td>
<td>Yes</td>
<td>No</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Solution 2: tryLock/unLock</td>
<td>No</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Solution 3: isolated</td>
<td>No</td>
<td>No</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Solution 4: object-based isolation</td>
<td>No</td>
<td>No</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>Solution 5: semaphores w/ FIFO queues</td>
<td>No</td>
<td>No</td>
<td>No</td>
<td>No</td>
</tr>
</tbody>
</table>
Acknowledgments for Today’s Lecture

- “Principles of Parallel Programming”, Calvin Lin & Lawrence Snyder
  — Includes resources available at http://www.pearsonhighered.com/educator/academic/product/0,3110,0321487907,00.html

- “Parallel Architectures”, Calvin Lin
  — Lectures 5 & 6, CS380P, Spring 2009, UT Austin


- MPI slides from “High Performance Computing: Models, Methods and Means”, Thomas Sterling, CSC 7600, Spring 2009, LSU
  — http://www.cct.lsu.edu/csc7600/coursemat/index.html

- mpiJava home page: http://www.hpjava.org/mpiJava.html

- MPI lectures given at Rice HPC Summer Institute 2009, Tim Warburton, May 2009
Cores communicate by reading and writing data in a “shared memory”

- Memory hierarchy for a single Intel Xeon (Nehalem) Quad-core processor chip
  —A STIC node contains TWO such chips, for a total of 8 cores
What is the cost of a Memory Access?

An example Memory Hierarchy

L0:
Registers

L1:
L1 cache (Static RAM)

L2:
L2 cache (Static RAM)

L3:
Main memory (Dynamic RAM)

L4:
Local secondary storage (local disks)

L5:
Remote secondary storage (tapes, distributed file systems, Web servers)

CPU registers hold words retrieved from L1 cache
L1 cache holds cache lines retrieved from L2 cache
L2 cache holds cache lines retrieved from main memory
Main memory holds disk blocks retrieved from local disks
Local disks hold files retrieved from disks on remote network servers

Smaller, faster, costlier per byte
Larger, slower, cheaper per byte

Source: http://www.cs.cmu.edu/afs/cs/academic/class/15213-f10/www/lectures/09-memory-hierarchy.pptx

COMP 322, Spring 2019 (M. Joyner, Z. Budimlić)
Organization of a Distributed-Memory Multiprocessor

Figure (a)
- Host node \((P_c)\) connected to a cluster of processor nodes \((P_0 \ldots P_m)\)
- Processors \(P_0 \ldots P_m\) communicate via an interconnection network which could be standard TCP/IP (e.g., for Map-Reduce) or specialized for high performance communication (e.g., for scientific computing)

Figure (b)
- Each processor node consists of a processor, memory, and a Network Interface Card (NIC) connected to a router node (R) in the interconnect

Processors communicate by sending messages via an interconnect
Message-Passing for Distributed-Memory Multiprocessors

- The logical view of a machine supporting the message-passing paradigm consists of $p$ processes, each with its own exclusive address space, that are capable of executing on different nodes in a distributed-memory multiprocessor.

  1. Each data element must belong to one of the partitions of the space; hence, data must be explicitly partitioned and placed.
  2. All interactions (read-only or read/write) require cooperation of two processes - the process that has the data and the process that wants to access the data.

- These two constraints, while onerous, make underlying costs very explicit to the programmer.

- In this loosely synchronous ("bulk synchronous") model, processes synchronize infrequently to perform interactions. Between these interactions, they execute completely asynchronously.
Data Distribution: Local View in Distributed-Memory Systems

Distributed memory
- Each process sees a local address space
- Processes send messages to communicate with other processes

Data structures
- Presents a Local View instead of Global View
- Programmer must make the mapping

![Global View and Local View](image)
MPI: The Message Passing Interface

• Sockets and Remote Method Invocation (RMI) are communication primitives used for distributed Java programs.
  — Designed for standard TCP/IP networks rather than high-performance interconnects

• The Message Passing Interface (MPI) standard was designed to exploit high-performance interconnects
  — MPI was standardized in the early 1990s by the MPI Forum—a substantial consortium of vendors and researchers
    − http://www-unix.mcs.anl.gov/mpi
  — It is an API for communication between nodes of a distributed memory parallel computer
  — The original standard defines bindings to C and Fortran (later C++)
    − Java support is available from a research project, mpiJava, developed at Indiana University 10+ years ago
      http://www.hpjava.org/mpiJava.html

• Most MPI programs are written using the single program multiple data (SPMD) model
SPMD Pattern

- **SPMD: Single Program Multiple Data**
- Run the same program on P processing elements (PEs)
- Use the “rank” … an ID ranging from 0 to (P-1) … to determine what computation is performed on what data by a given PE
  \[\Rightarrow\] you can think of the rank as the index of an implicit foralls across all PEs
- Different PEs can follow different paths through the same code
- Convenient pattern for hardware platforms that are not amenable to efficient forms of dynamic task parallelism
  - General-Purpose Graphics Processing Units (GPGPUs)
  - Distributed-memory parallel machines
- Key design decisions --- how should data and computation be distributed across PEs?
Using the Single Program Multiple Data (SPMD) model with a Local View

SPMD code

- Write one piece of code that executes on each processor

- Processors must communicate via messages for non-local data accesses

- Similar to communication constraint for actors — except that we allow hybrid combinations of task parallelism and actor parallelism in HJlib, but there is no integration (as yet) of HJlib or Java ForkJoin with mpiJava
The Minimal Set of MPI Routines (mpiJava)

- **MPI.Init(args)**
  - initialize MPI in each process

- **MPI.Finalize**
  - terminate MPI

- **MPI.COMM_WORLD.Size()**
  - number of processes in COMM_WORLD communicator

- **MPI.COMM_WORLD.Rank()**
  - rank of this process in COMM_WORLD communicator

**Note:**
- COMM_WORLD is the default communicator that includes all N processes, and numbers them with ranks from 0 to N-1
- The above are all static methods with names that don’t follow current coding conventions!
Our First MPI Program
 mpiJava version

1. import mpi.*;

2. class Hello {

3.     static public void main(String[] args) {
4.         // Init() be called before other MPI calls
5.         MPI.Init(args);
6.         int npes = MPI.COMM_WORLD.Size();
7.         int myrank = MPI.COMM_WORLD.Rank();
8.         System.out.println("My process number is " + myrank);
9.         MPI.Finalize(); // Shutdown and clean-up
10.     }
11. }

main() is enclosed in an implicit “forall” --- each process runs a separate instance of main() with “index variable” = myrank
Communicator is an internal object

- Communicator registration is like phaser registration, except that MPI does not support dynamic creation of new processes in a communicator

MPI programs are made up of communicating processes

Each process has its own address space containing its own attributes such as rank, size (and argc, argv, etc.)

MPI provides functions to interact with it

Default communicator is `MPI.COMM_WORLD`

- All processes are its members
- It has a size (the number of processes)
- Each process has a rank within it
- Can think of it as an ordered list of processes

Additional communicator(s) can co-exist

A process can belong to more than one communicator

Within a communicator, each process has a unique rank
Adding Send() and Recv() to the

- **MPI.Init(args)**
  - initialize MPI in each process
- **MPI.Finalize()**
  - terminate MPI
- **MPI.COMM_WORLD.Size()**
  - number of processes in COMM_WORLD communicator
- **MPI.COMM_WORLD.Rank()**
  - rank of this process in COMM_WORLD communicator
- **MPI.COMM_WORLD.Send()**
  - send message using COMM_WORLD communicator
- **MPI.COMM_WORLD.Recv()**
  - receive message using COMM_WORLD communicator
MPI Blocking Point to Point Communication: Basic Idea

• A very simple communication between two processes is:
  — process zero sends ten doubles to process one

• In MPI this is a little more complicated than you might expect.

• Process zero has to tell MPI:
  — to send a message to process one
  — that the message contains ten entries
  — the entries of the message are of type double
  — the message has to be tagged with a label (integer number)

• Process one has to tell MPI:
  — to receive a message from process zero
  — that the message contains ten entries
  — the entries of the message are of type double
  — the label that process zero attached to the message
mpiJava send and receive

- **Send and Recv methods in Comm object:**
  ```java
  void Send(Object buf, int offset, int count,
             Datatype type, int dest, int tag);
  Status Recv(Object buf, int offset, int count,
               Datatype type, int src, int tag);
  ```

- **The arguments** `buf`, `offset`, `count`, `type` describe the data buffer to be sent and received.

- **Both Send() and Recv() are blocking operations ==> potential for deadlock!**
  - Send() waits for a matching Recv() from its dest rank with matching type and tag
  - Recv() waits for a matching Send() from its src rank with matching type and tag
  — Analogous to a phaser-specific next operation between two tasks registered in SIG_WAIT mode

- The **Recv() method also returns a Status value, discussed later.**
Example of Send and Recv

1. import mpi.*;
2. class myProg {
3.   public static void main( String[] args ) {
4.       int tag0 = 0; int tag1 = 1;
5.       MPI.Init( args ); // Start MPI computation
6.       if ( MPI.COMM_WORLD.rank() == 0 ) { // rank 0 = sender
7.           int loop[] = new int[1]; loop[0] = 3;
8.           MPI.COMM_WORLD.Send( "Hello World!", 0, 12, MPI.CHAR, 1, tag0 );
9.           MPI.COMM_WORLD.Send( loop, 0, 1, MPI.INT, 1, tag1 );
10.       } else { // rank 1 = receiver
11.           int loop[] = new int[1]; char msg[] = new char[12];
12.           MPI.COMM_WORLD.Recv( msg, 0, 12, MPI.CHAR, 0, tag0 );
13.           MPI.COMM_WORLD.Recv( loop, 0, 1, MPI.INT, 0, tag1 );
14.           for ( int i = 0; i < loop[0]; i++ )
15.             System.out.println( msg );
16.       }
17.       MPI.Finalize( ); // Finish MPI computation
18.   }
19. }

Send() and Recv() calls are blocking operations