# COMP 515: Advanced Compilation for Vector and Parallel Processors

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https://wiki.rice.edu/confluence/display/PARPROG/COMP515



### Homework #3 (REMINDER)

#### 1. Solve exercise 5.6 in book

Your solution should be legal for all values of K (note that the value of K is invariant in loop I)

Exercise 5.6: What vector code should be generated for the following loop?

DO I = 1, 100  

$$A(I) = B(K) + C(I)$$
  
 $B(I+1) = A(I) + D(I)$   
END DO

Due on Oct 8<sup>th</sup>

#### Recap

- More transformations to expose more fine-grained parallelism
  - -Node Splitting
  - Recognition of Reductions
  - -Index-Set Splitting
  - -Run-time Symbolic Resolution
  - -Loop Skewing

**Previous lecture** 

This lecture

- Unified framework to generate vector code
- Note: these transformations are useful for generating other forms of parallel code as well (beyond vector)

#### **Run-time Symbolic Resolution**

"Breaking Conditions"

```
DO I = 1, N
 A(I+L) = A(I) + B(I)
ENDDO
Transformed to..
IF(L.LE.O .OR. L.GT.N) THEN
 A(L+1:N+L) = A(1:N) + B(1:N)
ELSE
 DO I = 1, N
    A(I+L) = A(I) + B(I)
 ENDDO
ENDIF
```

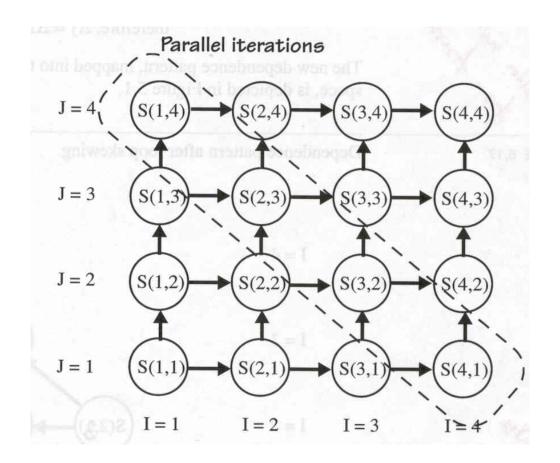
#### **Run-time Symbolic Resolution**

- Identifying minimum number of breaking conditions to break a recurrence is NP-hard
  - NOTE: in practice, this can be more important for conditions related to pointer aliasing than for array subscripts
- Heuristic:
  - Identify when a critical dependence can be conditionally eliminated via a breaking condition

Reshape Iteration Space to uncover parallelism

 Parallelism not apparent at loop level, and interchange doesn't help

Dependence Pattern before loop skewing



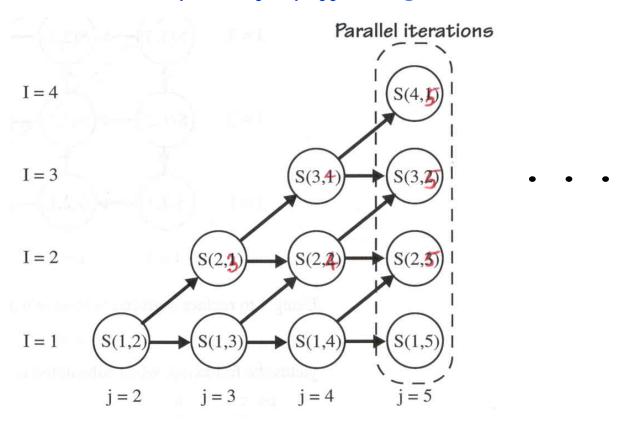
Do the following transformation called loop skewing

**ENDDO** 

Note: Direction Vector Changes, but statement body remains the same (Examples in textbook usually copy propagate J=jj-I in all uses of J)

Dependence pattern after loop skewing

-NOTE: Replace j by jj in figure below



```
DO I = 1, N ! DV = \{(<,<), (=,<)\}
  DO jj = I+1, I+N
S: A(I,jj-I) = A(I-1,jj-I) + A(I,jj-I-1)
  ENDDO
ENDDO
Loop interchange to..
DO jj = 2, N+N ! DV = { (<,<), (<, =) }
  DO I = max(1,jj-N), min(N,jj-1)
S: A(I,jj-I) = A(I-1,jj-I) + A(I,jj-I-1)
  ENDDO
ENDDO
Vectorize to..
DO jj = 2, N+N
  FORALL I = max(1,jj-N), min(N,jj-1)
S: A(I,jj-I) = A(I-1,jj-I) + A(I,jj-I-1)
  END FORALL
ENDDO
```

- Disadvantages:
  - Varying vector length
    - Not profitable if N is small
  - If vector startup time is more than speedup time, this is not profitable
  - Vector bounds must be recomputed on each iteration of outer loop
- Apply loop skewing if everything else fails
- We will later study Unimodular and Polyhedral transformations, which include generalizations of loop skewing

#### **Chapter 5: Putting It All Together**

- Good Part
  - Many transformations imply more choices to exploit parallelism
- Bad Part
  - -Choosing the right transformation
  - —How to automate transformation selection process?
  - -Interference between transformations

#### **Putting It All Together**

Example of Interference DO I = 1, N DO J = 1, MS(I) = S(I) + A(I,J)**ENDDO ENDDO** Sum Reduction gives.. DO I = 1, N S(I) = S(I) + SUM (A(I,1:M))**ENDDO** While Loop Interchange and Vectorization gives .. DO J = 1, N S(1:N) = S(1:N) + A(1:N,J)**ENDDO** 

#### Putting It All Together

- Any algorithm which tries to tie all transformations must
  - —Take a global view of transformed code
  - -Know the architecture of the target machine
- Goal of our algorithm
  - -Finding ONE good vector loop in each loop nest [works well for most vector register architectures]

#### **Unified Framework**

- Detection: finding ALL loops for EACH statement that can be run in vector
- Selection: choosing best loop for vector execution for EACH statement
- Transformation: carrying out the transformations necessary to vectorize the selected loop
- See Section 5.10 for details

#### **Performance on Benchmarks**

Vectorizing	Total			Dependence			Vectorization			Idioms			Completeness		
Compiler	V	P	N	V	P	N	V	P	N	V	P	N	V	P	N
PFC	70	6	24	17	0	7	25	4	5	5	0	10	23	2	2
Alliant FX/8, Fortran V4.0	68	5	27	19	0	5	20	5	9	10	0	5	19	0	8
Amdahl VP-E, Fortran 77	62	11	27	16	1	7	21	8	5	11	1	3	14	1	12
Ardent Titan-1	62	6	32	18	0	6	19	5	10	9	0	6	16	1	10
CDC Cyber 205, VAST-2	62	5	33	16	0	8	20	5	9	7	0	8	19	0	8
CDC Cyber 990E/995E	25	11	64	8	0	16	6	8	20	3	1	11	8	2	17
Convex C Series, FC 5.0	69	5	26	17	0	7	25	4	5	11	0	4	16	1	10
Cray series, CF77 V3.0	69	3	28	20	0	4	18	3	13	9	0	6	22	0	5
CRAX X-MP, CFT V1.15	50	1	49	16	0	8	12	1	21	10	0	5	12	0	15
Cray Series, CFT77 V3.0	50	1	49	17	0	7	8	1	25	7	0	8	18	0	9
CRAY-2, CFT2 V3.1a	27	1	72	5	0	19	3	1	30	8	0	7	11	0	16
ETA-10, FTN 77 V1.0	62	7	31	18	0	6	18	7	9	7	0	8	19	0	8
Gould NP1, GCF 2.0	60	7	33	14	0	10	19	7	8	8	0	7	19	0	8
Hitachi S-810/820,	67	4	29	14	0	10	24	4	6	14	0	1	15	0	12
IBM 3090/VF, VS Fortran	52	4	44	12	0	12	19	3	12	5	1	9	16	0	11
Intel iPSC/2-VX, VAST-2	56	8	36	15	0	9	17	8	9	6	0	9	18	0	9
NEC SX/2, F77/SX	66	5	29	17	0	7	21	5	8	12	0	3	16	0	11
SCS-40, CFT x13g	24	1	75	7	0	17	6	1	27	5	0	10	6	0	21
Stellar GS 1000, F77	48	11	41	14	0	10	20	9	5	4	1	10	10	1	16
Unisys ISP, UFTN 4.1.2	67	13	20	21	3	0	19	8	7	10	2	3	17	0	10

### Test 171: One example that PFC was unable to vectorize

```
DO I = 1, N

A(I*N) = A(I*N) + B(I)
ENDDO
```

#### **Coarse-Grain Parallelism**

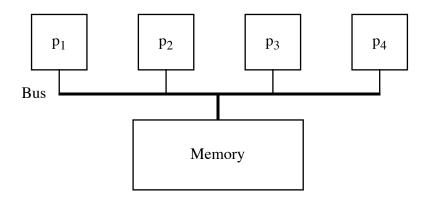
Chapter 6 of Allen and Kennedy

#### Introduction

- Previously, our transformations targeted vector and superscalar architectures.
- In Chapter 6, we worry about transformations for symmetric multiprocessor (multicore) machines.
- The difference between these transformations tends to be one of granularity.

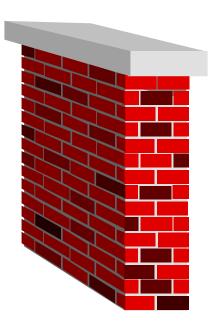
#### Review

- SMP machines have multiple processors all accessing a central memory.
- The processors are unrelated, and can run separate processes.
- Starting processes and synchonrization between processes is expensive.



#### **Synchronization**

- A basic synchronization element is the barrier at the end of a parallel loop.
- A barrier in a program forces all processes to reach a certain point before execution continues.
- Bus contention can cause slowdowns.



## Techniques for parallelizing a single loop

- Single loop methods
  - -Privatization
  - -Loop distribution
  - -Loop fusion
  - Alignment
  - -Code replication

#### Single Loops

- The analog of scalar expansion is privatization.
- Temporaries can be given separate namespaces for each iteration.

```
DOI = 1,N
                                     PARALLEL DO I = 1, N
S1
       T = A(I)
                                       PRIVATE t
S2
      A(I) = B(I)
                                 S1
                                       t = A(I)
S3
       B(I) = T
                                 S2
                                       A(I) = B(I)
    ENDDO
                                 S3
                                       B(I) = t
                                     ENDDO
```

#### **Privatization**

Definition: A scalar variable x in a loop L is said to be privatizable if every path from the loop entry to a use of x inside the loop passes through a definition of x.

Privatizability can be stated as a data-flow problem:

$$up(x) = use(x) \cup (!def(x) \cap \bigcup_{y \in succ(x)} up(y))$$
$$private(L) = !up(entry) \cap (\bigcup_{y \in I} def(y))$$

We can also do this by declaring a variable x private if its SSA graph doesn't contain a phi function at the entry.

#### **Course Schedule**

- No class on October 1 and October 8
- Individual project meetings will be scheduled during Oct 12-13