
COMP 322: Fundamentals of Parallel Programming

Lecture 13: Barriers (contd), Iterative Averaging Revisited

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<https://wiki.rice.edu/confluence/display/PARPROG/COMP322>

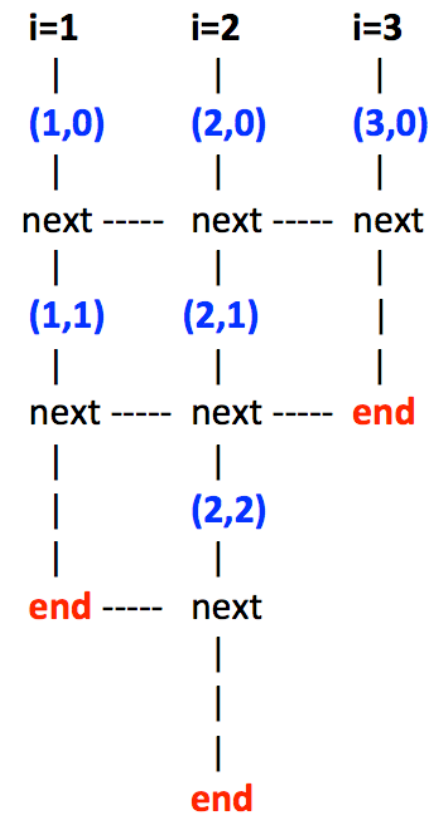


Worksheet #12: Forall Loops and Barriers

Draw a “barrier matching” figure similar to slide 23 for the code fragment below.

```
1. String[] a = { "ab", "cde", "f" };
2. . . . int m = a.length; . . .
3. forallPhased (0, m-1, (i) -> {
4.     for (int j = 0; j < a[i].length(); j++) {
5.         // forall iteration i is executing phase j
6.         System.out.println("(" + i + ", " + j + ")");
7.         next();
8.     }
9. });
```

Solution



Observation 1: Scope of synchronization for “next” is closest enclosing forall statement

```
1. forallPhased (0, m - 1, (i) -> {
2.   println("Starting forall iteration " + i);
3.   next(); // Acts as barrier for forall-i
4.   forallPhased (0, n - 1, (j) -> {
5.     println("Hello from task (" + i + ", " + j + ")");
6.     next(); // Acts as barrier for forall-j
7.     println("Goodbye from task (" + i + ", " + j + ")");
8.   } // forall-j
9.   next(); // Acts as barrier for forall-i
10.  println("Ending forall iteration " + i);
11.}); // forall-i
```



Observation 2: When a forall iteration terminates, other iterations do not wait for it at future barriers

1. `forallPhased (0, m - 1, (i) -> {`
 2. `forseq (0, i, (j) -> {`
 3. `// forall iteration i is executing phase j`
 4. `System.out.println("(" + i + "," + j + ")");`
 5. `next();`
 6. `});`
 7. `});`
- Outer forall-i loop has m iterations, 0...m-1
 - Inner sequential j loop has i+1 iterations, 0...i
 - Line 4 prints (task,phase) = (i, j) before performing a next operation.
 - Iteration i = 0 of the forall-i loop prints (0, 0), performs a next, and then terminates. Iteration i = 1 of the forall-i loop prints (1,0), performs a next, prints (1,1), performs a next, and then terminates. And so on.



Observation 3: Different forall iterations may perform “next” at different program points (barrier matching problem)

```
1. forallPhased (0, m-1, (i) -> {
2.     if (i % 2 == 1) { // i is odd
3.         oddPhase0(i);
4.         next();
5.         oddPhase1(i);
6.     } else { // i is even
7.         evenPhase0(i);
8.         next();
9.         evenPhase1(i);
10.    } // if-else
11. }); // forall
```

- Barrier operation synchronizes odd-numbered iterations at line 4 with even-numbered iterations in line 8
- next statement may even be in a method such as oddPhase1()



One-Dimensional Iterative Averaging Example Revisited

- Initialize a one-dimensional array of $(n+2)$ double's with boundary conditions, $\text{myVal}[0] = 0$ and $\text{myVal}[n+1] = 1$.
- In each iteration, each interior element $\text{myVal}[i]$ in $1..n$ is replaced by the average of its left and right neighbors.
 - Two separate arrays are used in each iteration, one for old values and the other for the new values
- After a sufficient number of iterations, we expect each element of the array to converge to $\text{myVal}[i] = i/(n+1)$
 - In this case, $\text{myVal}[i] = (\text{myVal}[i-1] + \text{myVal}[i+1])/2$, for all i in $1..n$

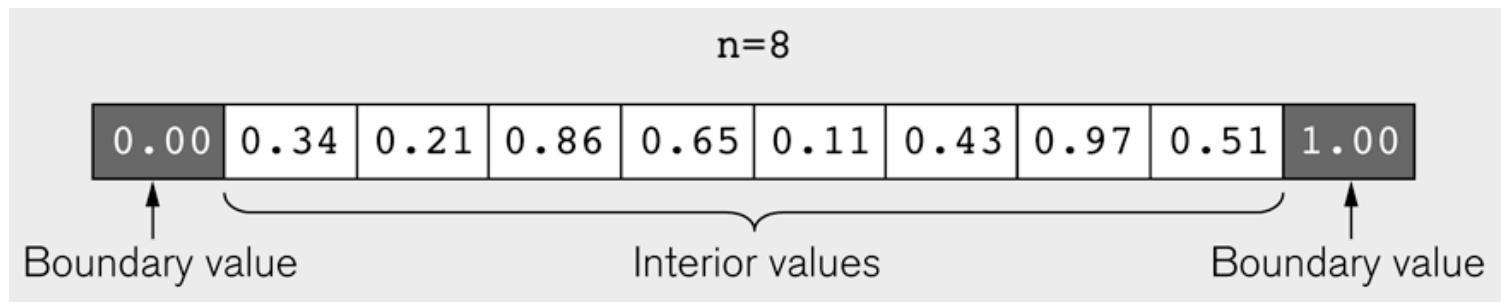


Illustration of an intermediate step for $n = 8$ (source: Figure 6.19 in Lin-Snyder book)



HJ code for One-Dimensional Iterative Averaging with forseq-forall structure

```
1. double[] myVal=new double[n+2]; myVal[n+1] = 1;
2. double[] myNew=new double[n+2];
3. forseq(0, m-1, (iter) -> {
4.     // Compute MyNew as function of input array MyVal
5.     forall(1, n, (j) -> { // Create n tasks
6.         myNew[j] = (myVal[j-1] + myVal[j+1])/2.0;
7.     }); // forall
8.     temp=myVal; myVal=myNew; myNew=temp;// Swap myVal & myNew;
9.     // myNew becomes input array for next iteration
10. }); // for
```

This program creates $m*n$ async tasks



HJ code for One-Dimensional Iterative Averaging with forseq-forallChunked structure

```
1. double[] myVal=new double[n+2]; myVal[n+1] = 1;
2. double[] myNew=new double[n+2];
3. int nc = numWorkerThreads();
4. forseq(0, m-1, (iter) -> {
5.     // Compute MyNew as function of input array MyVal
6.     forallChunked(1, n, n/nc, (j) -> { // Create nc tasks
7.         myNew[j] = (myVal[j-1] + myVal[j+1])/2.0;
8.     }); // forallChunked
9.     temp=myVal; myVal=myNew; myNew=temp;// Swap myVal & myNew;
10.    // myNew becomes input array for next iteration
11. }); // for
```

This program creates $m*nc$ async tasks



HJ code for One-Dimensional Iterative Averaging with forall-foreach structure and barriers

```
1. double[] gVal=new double[n+2]; gVal[n+1] = 1;
2. double[] gNew=new double[n+2];
3. forallPhased(1, n, (j) -> { // Create nc tasks
4.     // Initialize myVal and myNew as local pointers
5.     double[] myVal = gVal; double[] myNew = gNew;
6.     foreach(0, m-1, (iter) -> {
7.         // Compute MyNew as function of input array MyVal
8.         myNew[j] = (myVal[j-1] + myVal[j+1])/2.0;
9.         next(); // Barrier before executing next iteration of iter loop
10.        // Swap local pointers, myVal and myNew
11.        double[] temp=myVal; myVal=myNew; myNew=temp;
12.        // myNew becomes input array for next iteration
13.    }); // foreach
14. }); // forall
```

This program creates n async tasks, and performs m barrier operations per task



HJ code for One-Dimensional Iterative Averaging with grouped forall-foreach structure and barriers

```
1. double[] gVal=new double[n+2]; gVal[n+1] = 1;
2. double[] gNew=new double[n+2];
3. HJRegion1D iterSpace = newRectangularRegion1D(1,m);
4. int nc = numWorkerThreads();
5. forallPhased(1, nc, (jj) -> { // Create nc tasks
6.     // Initialize myVal and myNew as local pointers
7.     double[] myVal = gVal; double[] myNew = gNew;
8.     foreach(0, m-1, (iter) -> {
9.         foreach(myGroup(jj,iterSpace,nc), (j) -> {
10.            // Compute MyNew as function of input array MyVal
11.            myNew[j] = (myVal[j-1] + myVal[j+1])/2.0;
12.        }); // foreach
13.    next(); // Barrier before executing next iteration of iter loop
14.    // Swap local pointers, myVal and myNew
15.    double[] temp=myVal; myVal=myNew; myNew=temp;
16.    // myNew becomes input array for next iter
17. }); // foreach
18. }); // forall
```

This program creates nc async tasks, and performs m barrier operations per task



Single Program Multiple Data (SPMD) Parallel Programming Model

Basic idea

- Run the same code (program) on P workers
- Use the “rank” --- an ID ranging from 0 to (P-1) --- to determine what data is processed by which worker
 - Hence, “single-program” and “multiple-data”
 - Rank is equivalent to index in a top-level “forall (point[i] : [0:P-1])” loop
- Lower-level programming model than dynamic async/finish parallelism
 - Programmer’s code is essentially at the worker level (each forall iteration is like a worker), and work distribution is managed by programmer by using barriers and other synchronization constructs
 - Harder to program but can be more efficient for restricted classes of applications (e.g. for OneDimAveraging, but not for nqueens)
- Convenient for hardware platforms that are not amenable to efficient dynamic task parallelism
 - General-Purpose Graphics Processing Unit (GPGPU) accelerators
 - Distributed-memory parallel machines



HJ code for One-Dimensional Iterative Averaging with grouped forall-foreach structure and barriers

```
1. double[] gVal=new double[n+2]; gVal[n+1] = 1;
2. double[] gNew=new double[n+2];
3. HJRegion1D iterSpace = newRectangularRegion1D(1,m);
4. int nc = numWorkerThreads();
5. forallPhased(1, nc, (jj) -> { // Create nc tasks
6.     // Initialize myVal and myNew as local pointers
7.     double[] myVal = gVal; double[] myNew = gNew;
8.     foreach(0, m-1, (iter) -> {
9.         foreach(myGroup(jj,iterSpace,nc), (j) -> {
10.            // Compute MyNew as function of input array MyVal
11.            myNew[j] = (myVal[j-1] + myVal[j+1])/2.0;
12.        }); // foreach
13.        next(); // Barrier before executing next iteration of iter loop
14.        // swap local pointers, myVal and myNew
15.        double[] temp=myVal; myVal=myNew; myNew=temp;
16.        // myNew becomes input array for next iter
17.    }); // foreach
18. }); // forall
```

Instead of async-finish, this SPMD version creates one task per worker, uses myGroup() to distribute work, and use barriers to synchronize workers.