# **COMP 322: Fundamentals of Parallel Programming**

Lecture 30: Introduction to Message Passing Interface (MPI)

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https://wiki.rice.edu/confluence/display/PARPROG/COMP322



### **Acknowledgments for Today's Lecture**

- "Principles of Parallel Programming", Calvin Lin & Lawrence Snyder
  - —Includes resources available at <a href="http://www.pearsonhighered.com/educator/academic/product/0.3110.0321487907.00.html">http://www.pearsonhighered.com/educator/academic/product/0.3110.0321487907.00.html</a>
- "Parallel Architectures", Calvin Lin
  - -Lectures 5 & 6, CS380P, Spring 2009, UT Austin
  - -http://www.cs.utexas.edu/users/lin/cs380p/schedule.html
- Slides accompanying Chapter 6 of "Introduction to Parallel Computing", 2nd Edition, Ananth Grama, Anshul Gupta, George Karypis, and Vipin Kumar, Addison-Wesley, 2003
  - http://www-users.cs.umn.edu/~karypis/parbook/Lectures/AG/chap6\_slides.pdf
- MPI slides from "High Performance Computing: Models, Methods and Means", Thomas Sterling, CSC 7600, Spring 2009, LSU
  - http://www.cct.lsu.edu/csc7600/coursemat/index.html
- mpiJava home page: <a href="http://www.hpjava.org/mpiJava.html">http://www.hpjava.org/mpiJava.html</a>
- MPI lectures given at Rice HPC Summer Institute 2009, Tim Warburton, May 2009



## Worksheet #29: Characterizing Solutions to the Dining Philosophers Problem

For the five solutions studied in Lecture #29, indicate in the table below which of the following conditions are possible and why:

- 1. Deadlock: when all philosopher tasks are blocked
- 2. Livelock: when all philosopher tasks are executing (i.e., no philosopher is blocked) but ALL philosophers are starved (never get to eat)
- 3. Starvation: when one or more philosophers are starved (never get to eat)
- 4. Non-Concurrency: when more than one philosopher cannot eat at the same time, even when resources are available i.e., not being used

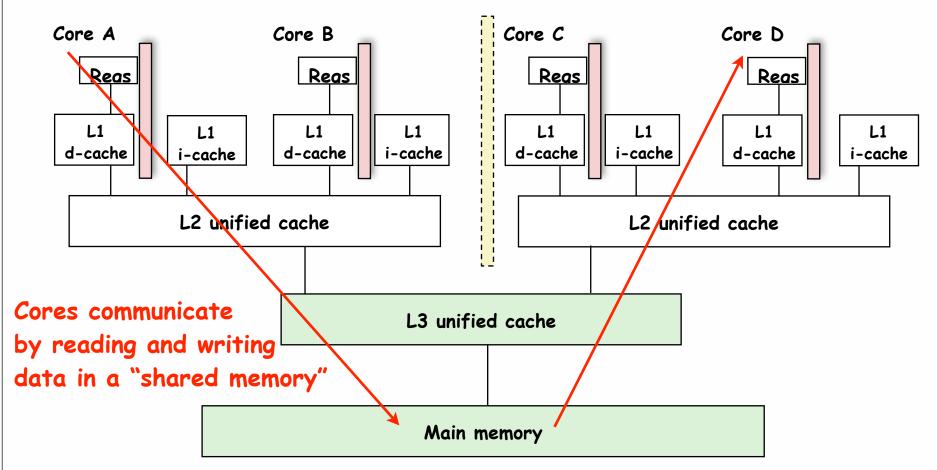
#### **NOTES:**

- Deadlock implies Starvation and Non-Concurrency
- Livelock implies Starvation and Non-Concurrency



|                           | Deadlock | Livelock | Starvation | Non-<br>concurrency |
|---------------------------|----------|----------|------------|---------------------|
| Solution 1:               | Yes      | No       | Yes        | Yes                 |
| synchronized              | (100%)   | (78%)    | (78%)      | (35%)               |
| Solution 2:               | No       | Yes      | Yes        | Yes                 |
| tryLock/<br>unLock        | (93%)    | (98%)    | (89%)      | (24%)               |
| Solution 3:               | No       | No       | Yes        | Yes                 |
| isolated                  | (100%)   | (96%)    | (87%)      | (94%)               |
| Solution 4:               | No       | No       | Yes        | No                  |
| object-based<br>isolation | (85%)    | (91%)    | (91%)      | (87%)               |
| Solution 5:               | No       | No       | No         | No                  |
| semaphores                | (93%)    | (93%)    | (67%)      | (63%)               |

# Organization of a Shared-Memory Multicore Symmetric Multiprocessor (SMP)



 Memory hierarchy for a single Intel Xeon Quad-core E5440 HarperTown processor chip

—A SUG@R node contains TWO such chips, for a total of 8 cores



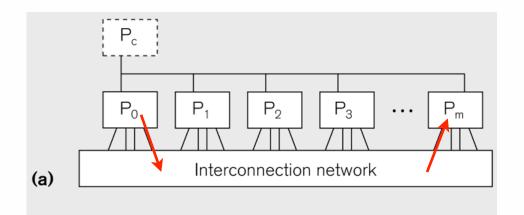
# Organization of a Distributed-Memory Multiprocessor

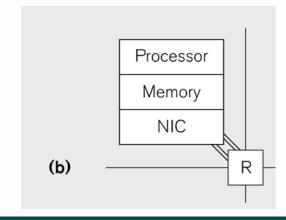
### Figure (a)

- Host node (Pc) connected to a cluster of processor nodes (P<sub>0</sub> ... P<sub>m</sub>)
- Processors P<sub>0</sub> ... P<sub>m</sub> communicate via a dedicated high-performance interconnection network (e.g., Infiniband)
  - —Supports much lower latencies and higher bandwidth than standard TCP/ IP networks

#### Figure (b)

• Each processor node consists of a processor, memory, and a Network Interface Card (NIC) connected to a router node (R) in the interconnect Processors communicate by sending messages via an interconnect







# Principles of Message-Passing Programming

- The logical view of a machine supporting the message-passing paradigm consists of *p* processes, each with its own exclusive address space.
  - 1. Each data element must belong to one of the partitions of the space; hence, data must be explicitly partitioned and placed.
  - 2. All interactions (read-only or read/write) require cooperation of two processes the process that has the data and the process that wants to access the data.
- These two constraints, while onerous, make underlying costs very explicit to the programmer.
- In this loosely synchronous model, processes synchronize infrequently to perform interactions. Between these interactions, they execute completely asynchronously.
- Most message-passing programs are written using the single program multiple data (SPMD) model.



### **SPMD Pattern**

- SPMD: Single Program Multiple Data
- Run the same program on P processing elements (PEs)
- Use the "rank" ... an ID ranging from 0 to (P-1) ... to determine what computation is performed on what data by a given PE
- Different PEs can follow different paths through the same code
- Convenient pattern for hardware platforms that are not amenable to efficient forms of dynamic task parallelism
  - —General-Purpose Graphics Processing Units (GPGPUs)
  - —Distributed-memory parallel machines
- Key design decisions --- how should data and computation be distributed across PEs?



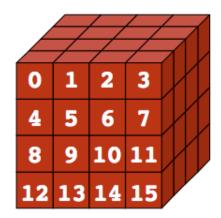
# Data Distribution: Local View in Distributed-Memory Systems

### **Distributed memory**

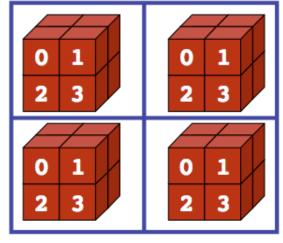
- Each process sees a local address space
- Processes send messages to communicate with other processes

#### Data structures

- Presents a Local View instead of Global View
- Programmer must make the mapping



**Global View** 



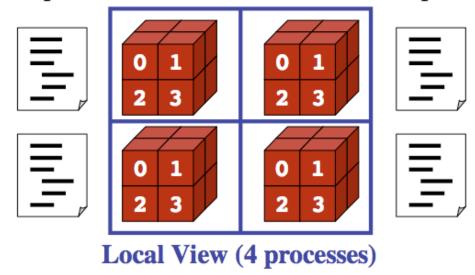
**Local View (4 processes)** 



# Using the Single Program Multiple Data (SPMD) model with a Local View

#### SPMD code

- Write one piece of code that executes on each processor



Processors must communicate via messages for non-local data accesses

 Similar to communication constraint for actors (except that we allow hybrid combinations of task parallelism and actor parallelism in HJ)



## **MPI: The Message Passing Interface**

- Sockets and Remote Method Invocation (RMI) are communication primitives used for distributed Java programs.
  - —Designed for standard TCP/IP networks rather than high-performance interconnects
- The Message Passing Interface (MPI) standard was designed to exploit high-performance interconnects
  - —MPI was standardized in the early 1990s by the MPI Forum—a substantial consortium of vendors and researchers
    - http://www-unix.mcs.anl.gov/mpi
  - —It is an API for communication between nodes of a distributed memory parallel computer
  - —The original standard defines bindings to C and Fortran (later C++)
    - Java support is available from a research project, mpiJava, developed at Indiana University 10+ years ago
      - http://www.hpjava.org/mpiJava.html



### **Features of MPI**

- MPI is a platform for Single Program Multiple Data (SPMD)
   parallel computing on distributed memory architectures, with an
   API for sending and receiving messages
- It includes the abstraction of a "communicator", which is like an N-way communication channel that connects a set of N cooperating processes (analogous to a phaser)
- It also includes explicit datatypes in the API, that are used to describe the contents of communication buffers.



### The Minimal Set of MPI Routines (mpiJava)

- MPI.Init(args)
  - —initialize MPI in each process
- MPI.Finalize()
  - —terminate MPI
- MPI.COMM\_WORLD.Size()
  - —number of processes in COMM\_WORLD communicator
- MPI.COMM\_WORLD.Rank()
  - —rank of this process in COMM\_WORLD communicator
  - Note:
    - —In this subset, processes act independently with no information communicated among the processes.
    - —"embarrassingly parallel", Cleve Moler.



# Our First MPI Program (mpiJava version)

main() is enclosed in an

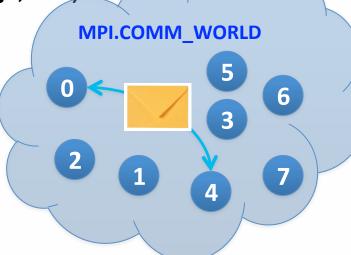
```
implicit "forall" --- each
                                        process runs a separate
                                        instance of main() with
1.import mpi.*;
                                        "index variable" = myrank
2 class Hello {
3.
      static public void main(String[] args) {
4.
         // Init() be called before other MPI calls
5.
         MPI.Init(args); /
6.
         int npes = MPI.COMM WORLD.Size()
7.
         int myrank = MPI.COMM WORLD.Rank() ;
8.
         System.out.println("My process number is " + myrank);
9.
10.
         MPI.Finalize(); // Shutdown and clean-up
11.}
```

### **MPI Communicators**

- Communicator is an internal object
  - Communicator registration is like phaser registration, except that MPI does not support dynamic parallelism
- MPI programs are made up of communicating processes

• Each process has its own address space containing its own attributes such as rank, size (and argc, argv, etc.)

- MPI provides functions to interact with it
- Default communicator is MPI.COMM\_WORLD
  - -All processes are its members
  - —It has a size (the number of processes)
  - -Each process has a rank within it
  - —Can think of it as an ordered list of processes
- Additional communicator(s) can co-exist
- A process can belong to more than one communicator
- Within a communicator, each process has a unique rank





## Adding Send() and Recv() to the Minimal Set of MPI Routines (mpiJava)

- MPI.Init(args)
  - —initialize MPI in each process
- MPI.Finalize()
  - —terminate MPI
- MPI.COMM\_WORLD.Size()
  - —number of processes in COMM\_WORLD communicator
- MPI.COMM\_WORLD.Rank()
  - —rank of this process in COMM\_WORLD communicator
- MPI.COMM\_WORLD.Send()
  - —send message using COMM\_WORLD communicator
- MPI.COMM\_WORLD.Recv()
  - —receive message using COMM\_WORLD communicator

Pointtopoint commn

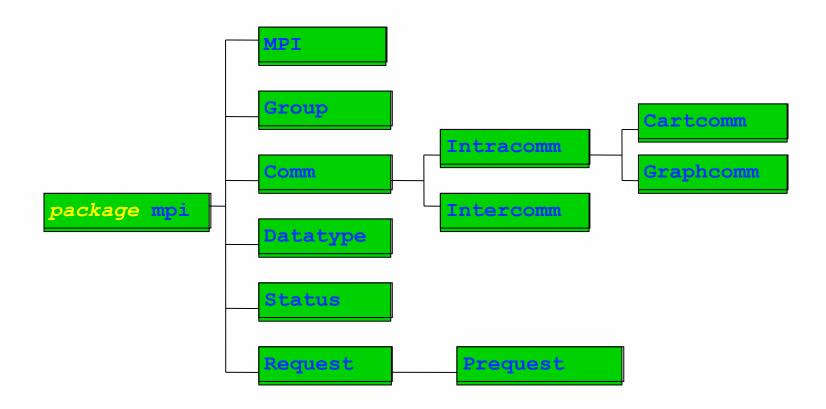


## MPI Blocking Point to Point Communication: Basic Idea

- A very simple communication between two processes is:
  - -process zero sends ten doubles to process one
- In MPI this is a little more complicated than you might expect.
- Process zero has to tell MPI:
  - —to send a message to process one
  - —that the message contains ten entries
  - —the entries of the message are of type double
  - —the message has to be tagged with a label (integer number)
- Process one has to tell MPI:
  - —to receive a message from process zero
  - —that the message contains ten entries
  - —the entries of the message are of type double
  - —the label that process zero attached to the message



## mpiJava Class hierarchy





### mpiJava send and receive

Send and receive members of Comm:

```
void Send(Object buf, int offset, int count, Datatype type, int dst, int tag);
```

Status Recv(Object buf, int offset, int count, Datatype type, int src, int tag);

- The arguments buf, offset, count, type describe the data buffer the storage of the data that is sent or received. They will be discussed on the next slide.
- dst is the rank of the destination process relative to this communicator. Similarly in Recv(), src is the rank of the source process.
- An arbitrarily chosen tag value can be used in Recv() to select between several incoming messages: the call will wait until a message sent with a matching tag value arrives.
- The Recv() method returns a Status value, discussed later.
- Both Send() and Recv() are <u>blocking</u> operations by default
  - —Analogous to a phaser next operation



### **Example of Send and Recv**

```
1.import mpi.*;
2. class myProq {
   public static void main( String[] args ) {
     int tag0 = 0; int tag1 = 1;
5.
     MPI.Init( args );
                       // Start MPI computation
     if ( MPI.COMM WORLD.rank() == 0 ) { // rank 0 = sender
6.
       int loop[] = new int[1]; loop[0] = 3;
7.
8.
       MPI.COMM WORLD.Send( "Hello World!", 0, 12, MPI.CHAR, 1, tag0 );
9.
       MPI.COMM WORLD.Send( loop, 0, 1, MPI.INT, 1, tag1 );
                                         // rank 1 = receiver
10.
      } else {
11.
        int loop[] = new int[1]; char msg[] = new char[12];
12.
        MPI.COMM WORLD.Recv( msq, 0, 12, MPI.CHAR, 0, tag0 );
13.
        MPI.COMM WORLD.Recv( loop, 0, 1, MPI.INT, 0, tag1 );
14.
        for ( int i = 0; i < loop[0]; i++ ) System.out.println( msq );
15.
16.
      MPI.Finalize( );
                         // Finish MPI computation
17. }
18.}
```

Send() and Recv() calls are blocking operations by default



### Worksheet #30: MPI send and receive

| Name:       | Netid:   |
|-------------|--|
| 1. in       | t a[], b[];  |
| 2           | •  |
| 3. if       | (MPI.COMM_WORLD.rank() == 0) {                                       |
| 4.          | <pre>MPI.COMM_WORLD.Send(a, 0, 10, MPI.INT, 1, 1);</pre>             |
| <b>5.</b>   | <pre>MPI.COMM_WORLD.Send(b, 0, 10, MPI.INT, 1, 2);</pre>             |
| <b>6.</b> } |  |
| 7. el       | se {   |
| 8.          | <pre>Status s2 = MPI.COMM_WORLD.Recv(b, 0, 10, MPI.INT, 0, 2);</pre> |
| 9.          | <pre>Status s1 = MPI.COMM_WORLD.Recv(a, 0, 10, MPI_INT, 0, 1);</pre> |
| 10.         | <pre>System.out.println("a = " + a + " ; b = " + b);</pre>           |
| 11.}        |  |
| 12          |  |

In the space below, indicate what values you expect the print statement in line 10 to output, assuming that the program is executed with two MPI processes.

