# COMP 322: Fundamentals of Parallel Programming

# Lecture 29: Parallel Design Patterns, Safety and Liveness Properties

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https://wiki.rice.edu/confluence/display/PARPROG/COMP322



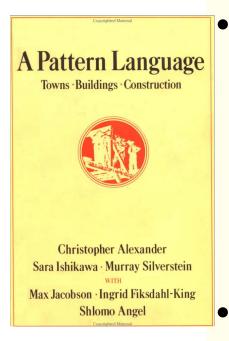
#### Worksheet #28 solution: use of tryLock()

Extend the transferFunds() method from Lecture 26 (shown below) to use j.u.c. locks with tryLock() instead of synchronized, and to return a boolean value --- true if it succeeds in obtaining both locks and performing the transfer, and false otherwise. Assume that each Account object contains a reference to a dedicated ReentrantLock object. Sketch your answer below using pseudocode. Can you create a deadlock with multiple calls to transferFunds() in parallel?

```
1. public boolean transferFunds (Account from, Account to,
2.
                                int amount) {
3.
    // Assume that each Account object has a lock field of
4.
    // a type/class that implements java.util.concurrent.locks.Lock
5.
    // Assume that no exception can be thrown in this code
6.
    // Calls to this method can never lead to a deadlock
7.
    if (! from.lock.trylock()) return false;
8.
    if (! to.lock.trylock()) { from.lock.unlock(); return false; }
9.
    from.subtractFromBalance(amount); to.addToBalance(amount);
10.
    // NOTE: unlock() should be in try-catch-finally for robustness
11.
    from.lock.unlock(); to.lock.unlock();
12.
   return true;
13. }
```



## **Design Patterns = formal discipline**



- Christopher Alexander's approach to (civil) architecture:
  - A design pattern "describes a problem which occurs over and over again in our environment, and then describes the core of the solution to that problem, in such a way that you can use this solution a million times over, without ever doing it the same way twice." Page x, A Pattern Language, Christopher Alexander, 1977
  - A pattern language is an organized way of tackling an architectural problem using patterns

Elements of Reusable Object-Oriented Software

Erich Gamma Richard Helm

Ralph Johnson

Foreword by Grady Booch

 The Design Patterns book turned object oriented design from an "art" to a systematic design discipline.



## Example GODD Dates by Example: Visitor

```
1. class Employee {
    private int vacationDays; private String SSN;
    public void accept(Visitor v) { v.visit(this); }
4. . . .
5. }
6. abstract class Visitor {
7. public abstract void visit(Employee emp);
8. }
9. class VacationVisitor extends Visitor {
10. private int totalDays;
11. public VacationVisitor() { total_days = 0; }
12. public void visit(Employee emp) {
13. totalDays += emp.getVacationDays();
14. }
     public int getTotalDays() { return totalDays; }
15.
16.}
17....
18. Vacation V is itor V = new V acation V is itor();
19.emp1.accept(v); emp2.accept(v); ...
20.... v.getTotalDays() ...
```



### **Patterns in Parallel Programming**

- Can a pattern language/taxonomy providing guidance for the entire development process make parallel programming easier?
  - Need to identify basic patterns, along with refinements (usually for efficiency)
  - By relating HJ constructs to parallel programming patterns, you can apply HJ concepts to any parallel programming model you encounter in the future
- Algorithmic Patterns
  - Selection of task and data decompositions to solve a given problem in parallel
    - Task decomposition = identification of parallel steps
    - Data decomposition = partitioning of data into task-local vs. shared storage classes
  - Examples: Parallel Loops, Parallel Tasks, Reductions, Dataflow, Pipeline



# Selecting the Right Pattern (adapted from page 9, Parallel Programming w/ Microsoft .Net)

Application characteristics	Algorithmic pattern	Relevant HJ constructs
Sequential loop with independent iterations	1) Parallel Loop	forall, forasync
Independent operations with well-defined control flow	2) Parallel Task	async, finish
Aggregating data from independent tasks/iterations	3) Parallel Aggregation (reductions)	finish accumulators
Ordering of steps based on data flow constraints	4) Futures	futures, data-driven tasks
Divide-and-conquer algorithms with recursive data structures	5) Dynamic Task Parallelism	async, finish
Repetitive operations on data streams	6) Pipelines	phasers, actors



### How to select parallel constructs in general?

- 1. Think of how to decompose your program into tasks
  - ⇒ async, future
- 2. Think of how to synchronize task creation and termination
  - ⇒ finish, future-get, async-await
- 3. Think of where multiple tasks need to operate on shared data
  - **⇒ Deterministic sharing: finish accumulators**
  - ⇒ Nondeterministic sharing: atomic variables, isolated, actors
- 4. Think of how to make your program more efficient
  - ⇒ Recursive tasks: seq clause
  - ⇒ Parallel loops: iteration grouping (chunking)
  - ⇒ SPMD model: replace synchronizations in #2 by barriers/phasers
  - ⇒ Isolated: use of atomic variables or object-based isolation
- 5. Think of when you need lower-level control beyond HJ-lib (should be rare)
  - **⇒ Time-outs: Java threads and locks**
  - ⇒ Advanced locking: Java locks with tryLock()



### Safety vs. Liveness

- In a concurrent setting, we need to specify both the safety and the liveness properties of an object
- Need a way to define
  - Safety: when an implementation is functionally correct (does not produce a wrong answer)
  - Liveness: the conditions under which it guarantees progress (completes execution successfully)

- Data race freedom is a desirable safety property for most parallel programs
- Linearizability is a desirable safety property for most concurrent objects



#### Liveness

- Liveness = a program's ability to make progress in a timely manner
- Is termination a requirement for liveness?
  - But some applications are designed to be non-terminating
- Different levels of liveness guarantees (from weaker to stronger)
  - 1. Deadlock freedom
  - 2. Livelock freedom
  - 3. Starvation freedom
  - 4. Bounded wait



# Terminating Parallel Program Executions

- A parallel program execution is terminating if all sequential tasks in the program terminate
- Example of a nondeterministic data-race-free program with a nonterminating execution

```
    p.x = false;
    finish {
    async { // S1
    boolean b = false; do { isolated b = p.x; } while (! b);
    }
    isolated p.x = true; // S2
    } // finish
```

- Some executions of this program may be terminating, and some not
- Cannot assume in general that statement S2 will ever get a chance to execute if async S1
  is nonterminating e.g., consider case when program is run with one worker



# 1. Deadlock-Free Parallel Program Executions

- A parallel program execution is deadlock-free if no task's execution remains incomplete due to it being blocked awaiting some condition
- Example of a program with a deadlocking execution

```
DataDrivenFuture left = new DataDrivenFuture();
DataDrivenFuture right = new DataDrivenFuture();
finish {
    async await ( left ) right.put(rightBuilder()); // Task1
async await ( right ) left.put(leftBuilder()); // Task2
}
```

- In this case, Task1 and Task2 are in a deadlock cycle.
  - Three constructs that can lead to deadlock in HJ: async await, finish + actors, explicit phaser wait (instead of next)
  - There are many mechanisms that can lead to deadlock cycles in other programming models (e.g., thread join, synchronized, locks in Java)



# 2. Livelock-Free Parallel Program Executions

- A parallel program execution exhibits livelock if two or more tasks repeat the same interactions without making any progress (special case of nontermination)
- Livelock example:

```
// Task 1
incrToTwo(AtomicInteger ai) {
   // top top top the content of the
```

- Many well-intended approaches to avoid deadlock result in livelock instead
- Any data-race-free HJ program without isolated/atomic-variables/actors is guaranteed to be livelock-free (may be nonterminating in a single task, however)



# 3. Starvation-Free Parallel Program Executions

- A parallel program execution exhibits starvation if some task is repeatedly denied the opportunity to make progress
  - Starvation-freedom is sometimes referred to as "lock-out freedom"
  - Starvation is possible in HJ programs, since all tasks in the same program are assumed to be cooperating, rather than competing
    - If starvation occurs in a deadlock-free HJ program, the "equivalent" sequential program must be non-terminating
- Classic source of starvation: "Priority Inversion" problem for OS threads
  - Thread A is at high priority, waiting for result or resource from Thread C at low priority
  - Thread B at intermediate priority is CPU-bound
  - Thread C never runs, hence thread A never runs
  - Fix: when a high priority thread waits for a low priority thread, boost the priority of the low-priority thread



### **Related Concepts: Progress Condition**

- A resource is said to be obstruction-free if it is deadlock-free
- A resource is said to be lock-free if it is livelock-free and deadlockfree
- A resource is said to be wait-free if it is starvation-free, livelock-free, and deadlock-free
  - Question: how to bound the wait duration?



#### 4. Bounded Wait

- A parallel program execution exhibits bounded wait if each task requesting a resource should only have to wait for a bounded number of other tasks to "cut in line" i.e., to gain access to the resource after its request has been registered.
- If bound = 0, then the program execution is fair



### A metaphor for Bounded Wait



- Progress: If no process is waiting in its critical section and several processes are trying to get into their critical section, then entry to the critical section cannot be postponed indefinitely
- Bounded Wait: A process requesting access to a resource should only have to wait for a bounded number of other processes to access the resource that requested access after it

A "cut-through" could cause unbounded wait for folks in the loop!

