

COMP 322: Fundamentals of Parallel Programming

Lecture 8: Computation Graphs, Ideal Parallelism

Mack Joyner and Zoran Budimlić
{mjoyner, zoran}@rice.edu

<http://comp322.rice.edu>



Computation Graphs

- A Computation Graph (CG) captures the dynamic execution of a parallel program, for a specific input
- CG nodes are “steps” in the program’s execution
 - A step is a sequential subcomputation without any spawned, begin-finish or end-finish operations
- CG edges represent ordering constraints
 - “Continue” edges define sequencing of steps within a task
 - “Spawn” edges connect parent tasks to child spawned tasks
 - “Join” edges connect the end of each spawned task to its IEF’s end-must finish operations
- All computation graphs must be acyclic
 - It is not possible for a node to depend on itself
- Computation graphs are examples of “directed acyclic graphs” (DAGs)

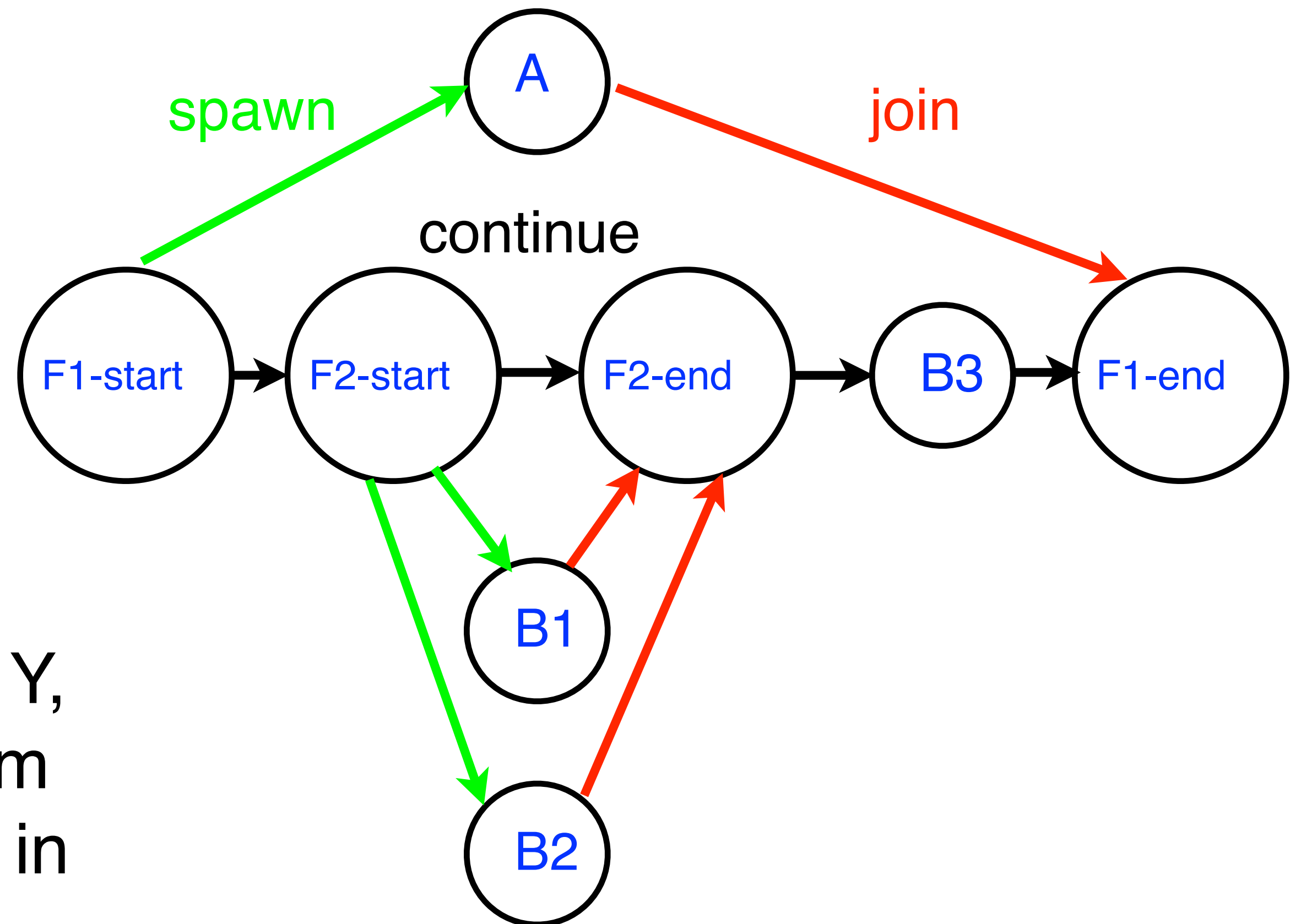


Which statements can potentially be executed in parallel with each other?

1. `must finish { // F1`
2. `spawn { A; }`
3. `must finish { // F2`
4. `spawn { B1; }`
5. `spawn { B2; }`
6. `} // F2`
7. `B3;`
8. `} // F1`

Key idea: If two statements, X and Y, have *no path of directed edges* from one to the other, then they can run in parallel with each other.

Computation Graph



Computational Graph Exercise

Assume you have 2 washers and 2 dryers. Assume there's 0 cost to spawn a task.

Place “must finish” blocks and “spawn” blocks around the following tasks:

1. Run load 1 in washer (LW1)
2. Run load 2 in washer (LW2)
3. Run load 1 in dryer (LD1)
4. Run load 2 in dryer (LD2)



Computational Graph Exercise (Solution #1)

Assume you have 2 washers and 2 dryers. Assume there's 0 cost to spawn a task.

Place “must finish” blocks and “spawn” around the following tasks:

1. must finish { // F1
2. spawn { Run load 1 in washer (LW1) }
3. spawn { Run load 2 in washer (LW2) }
- 4.} // F1
5. spawn { Run load 1 in dryer (LD1) }
6. spawn { Run load 2 in dryer (LD2) }



Computational Graph Exercise (Solution #2)

Assume you have 2 washers and 2 dryers. Assume there's 0 cost to spawn a task.

Place “must finish” blocks and “spawn” around the following tasks:

1. must finish { // F1
2. spawn { Run load 1 in washer (LW1); Run load 1 in dryer (LD1) }
3. spawn { Run load 2 in washer (LW2); Run load 2 in dryer (LD2) }
4. } // F1



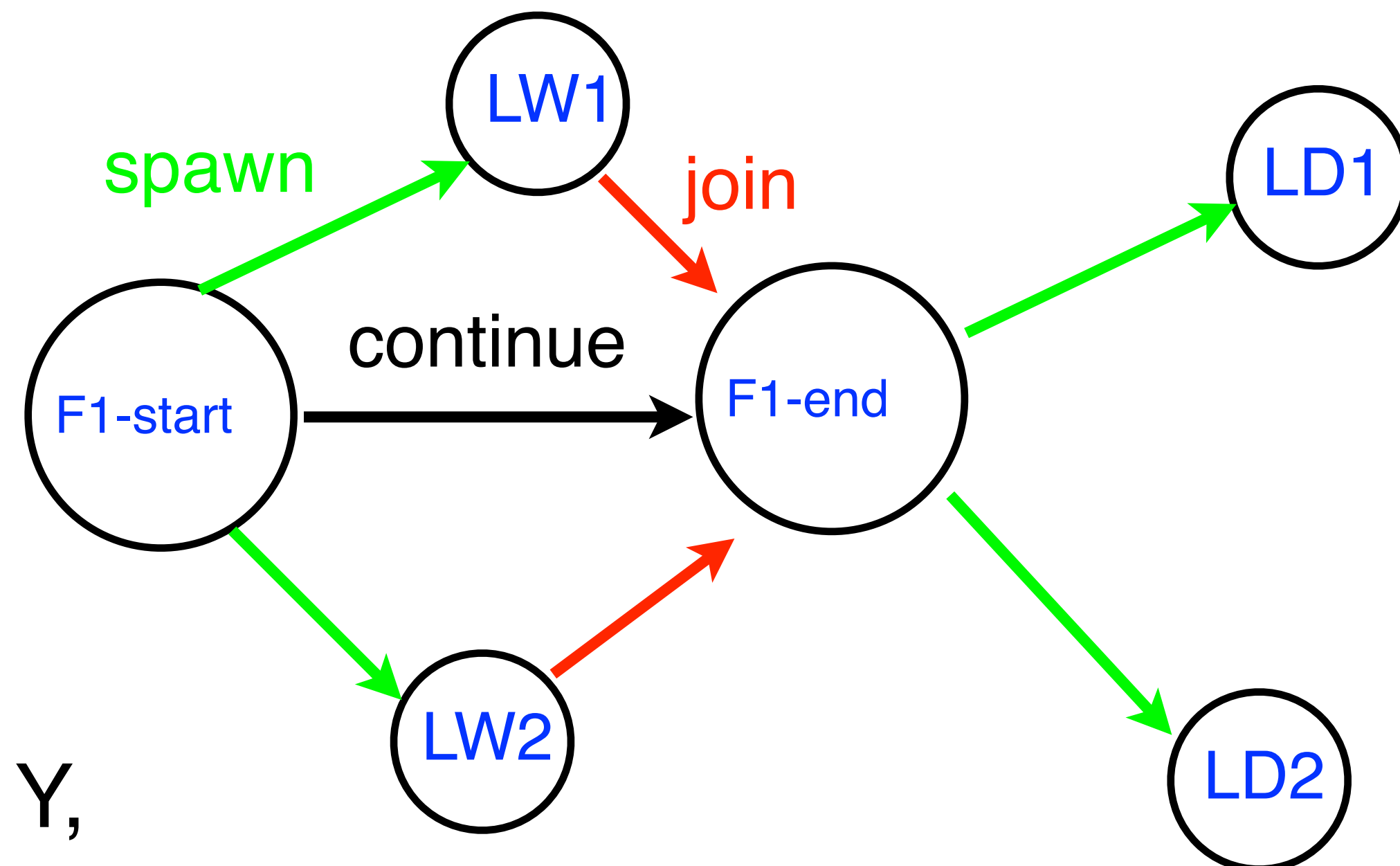
Draw Computation Graph for Solution



Draw Computation Graph for Solution #1

1. `must finish { // F1`
2. `spawn LW1;`
3. `spawn LW2;`
4. `}` // F1
5. `spawn LD1;`
6. `spawn LD2;`

Computation Graph



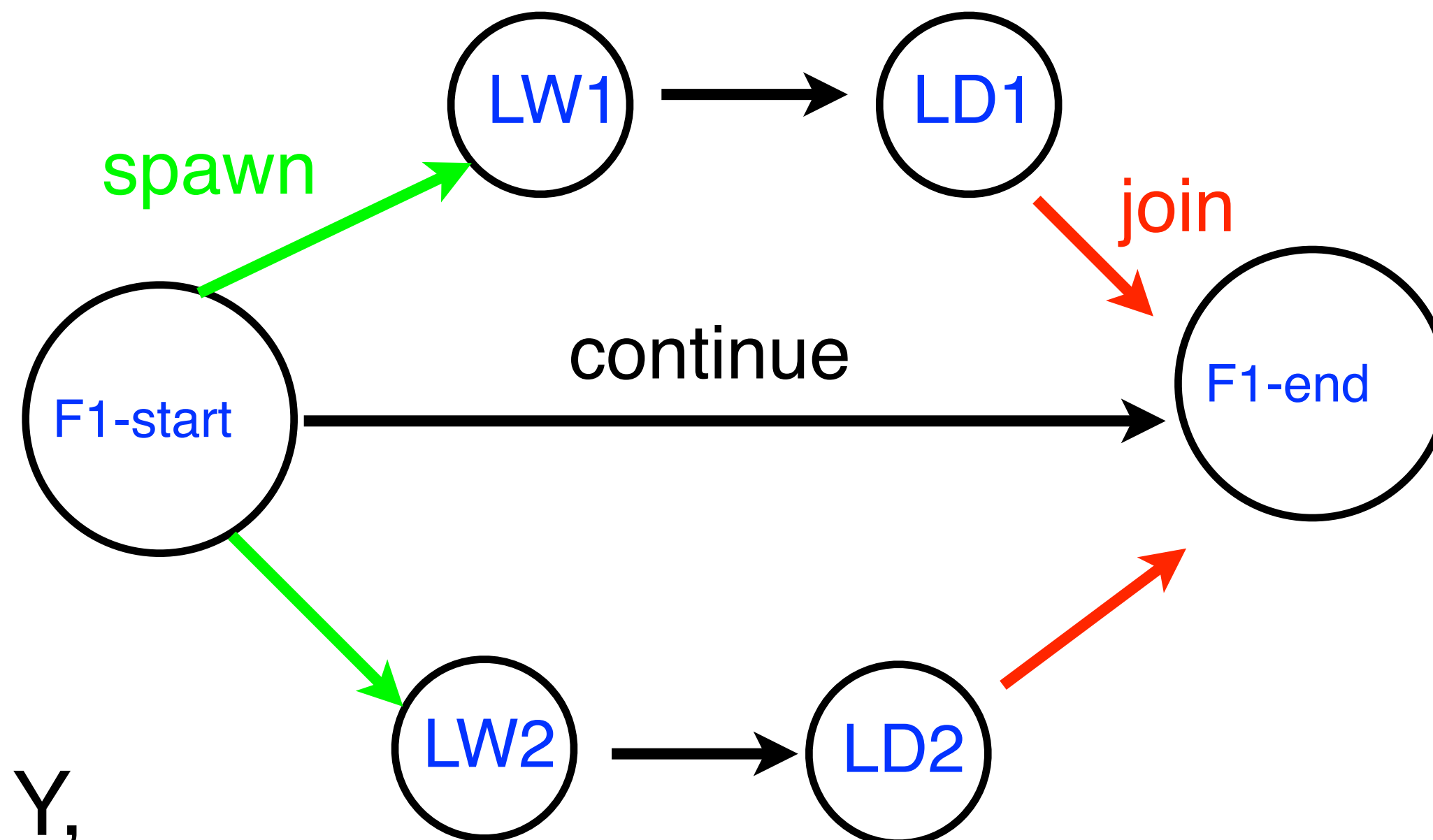
Key idea: If two statements, X and Y, have *no path of directed edges* from one to the other, then they can run in parallel with each other.



Draw Computation Graph for Solution #2

1. `must finish { // F1`
2. `spawn { LW1; LD1 }`
3. `spawn { LW2; LD2 }`
4. `} // F1`

Computation Graph



Key idea: If two statements, X and Y, have *no path of directed edges* from one to the other, then they can run in parallel with each other.

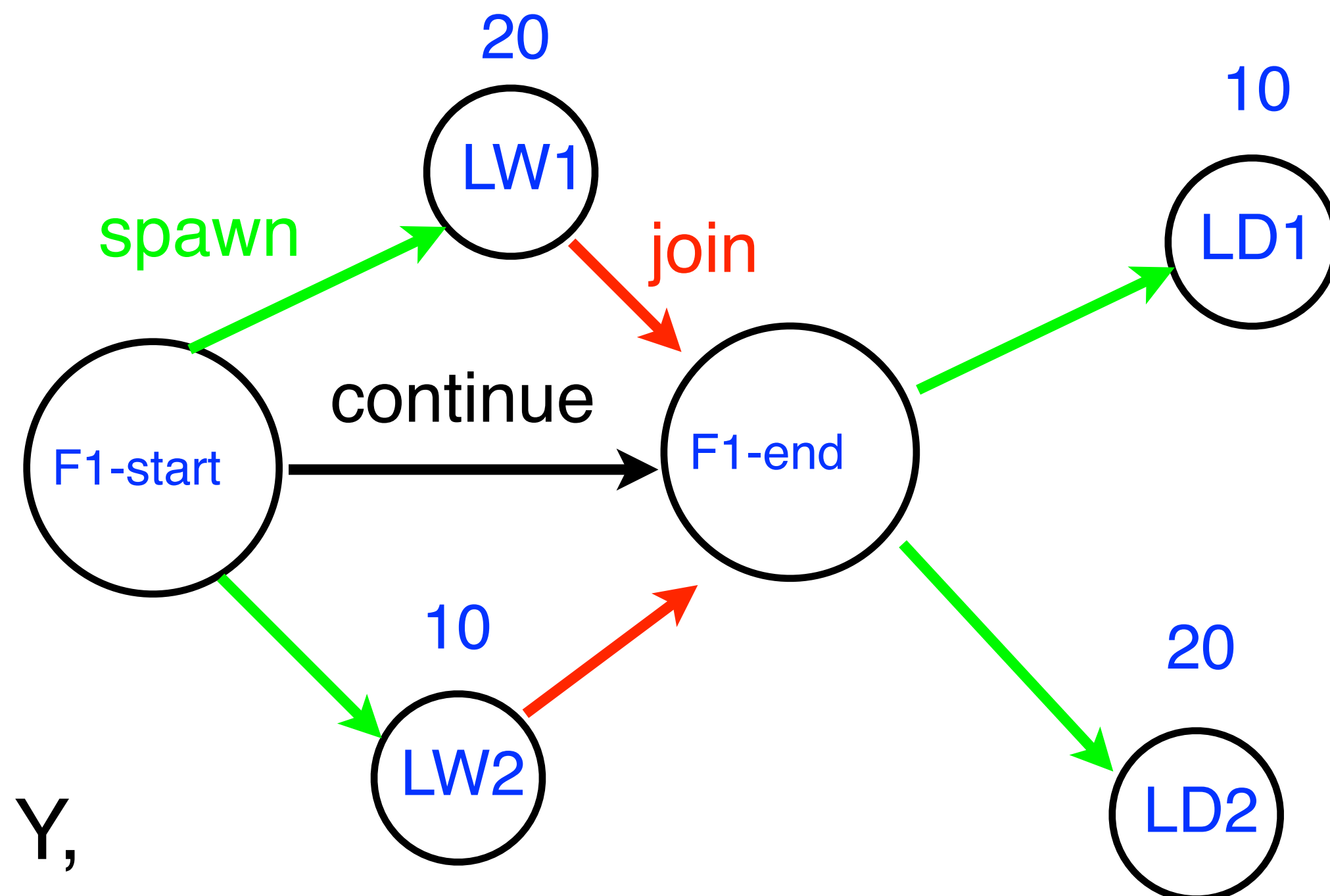
Which solution is better?



Draw Computation Graph for Solution #1

1. `must finish { // F1`
2. `spawn LW1;`
3. `spawn LW2;`
4. `}` // F1
5. `spawn LD1;`
6. `spawn LD2;`

Computation Graph



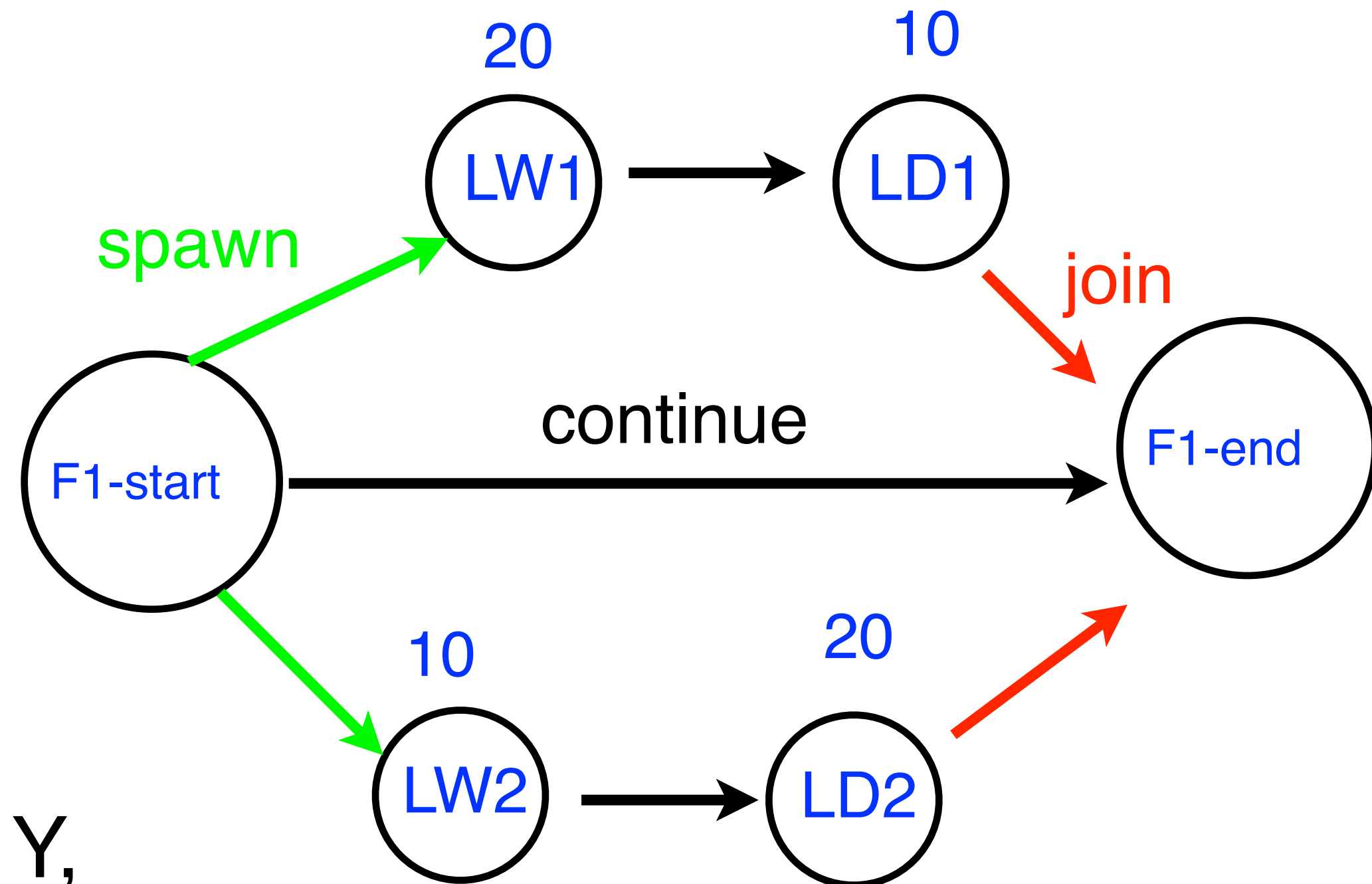
Key idea: If two statements, X and Y, have *no path of directed edges* from one to the other, then they can run in parallel with each other.



Draw Computation Graph for Solution #2

1. `must finish { // F1`
2. `spawn { LW1; LD1 }`
3. `spawn { LW2; LD2 }`
4. `} // F1`

Computation Graph



Key idea: If two statements, X and Y, have *no path of directed edges* from one to the other, then they can run in parallel with each other.



Complexity Measures for Computation Graphs

Define

- $\text{TIME}(N)$ = execution time of node N
- $\text{WORK}(G)$ = sum of $\text{TIME}(N)$, for all nodes N in CG G
 - $\text{WORK}(G)$ is the total work to be performed in G
- $\text{CPL}(G)$ = length of a longest path in CG G , when adding up execution times of all nodes in the path
 - Such paths are called *critical paths*
 - $\text{CPL}(G)$ is the length of these paths (critical path length, also referred to as the *span* of the graph)
 - $\text{CPL}(G)$ is also the shortest possible execution time for the computation graph



Ideal Parallelism

- Define **ideal parallelism** of Computation G Graph as the ratio, $WORK(G)/CPL(G)$
- Ideal Parallelism only depends on the computation graph, and is the speedup that you can obtain with an unbounded number of processors

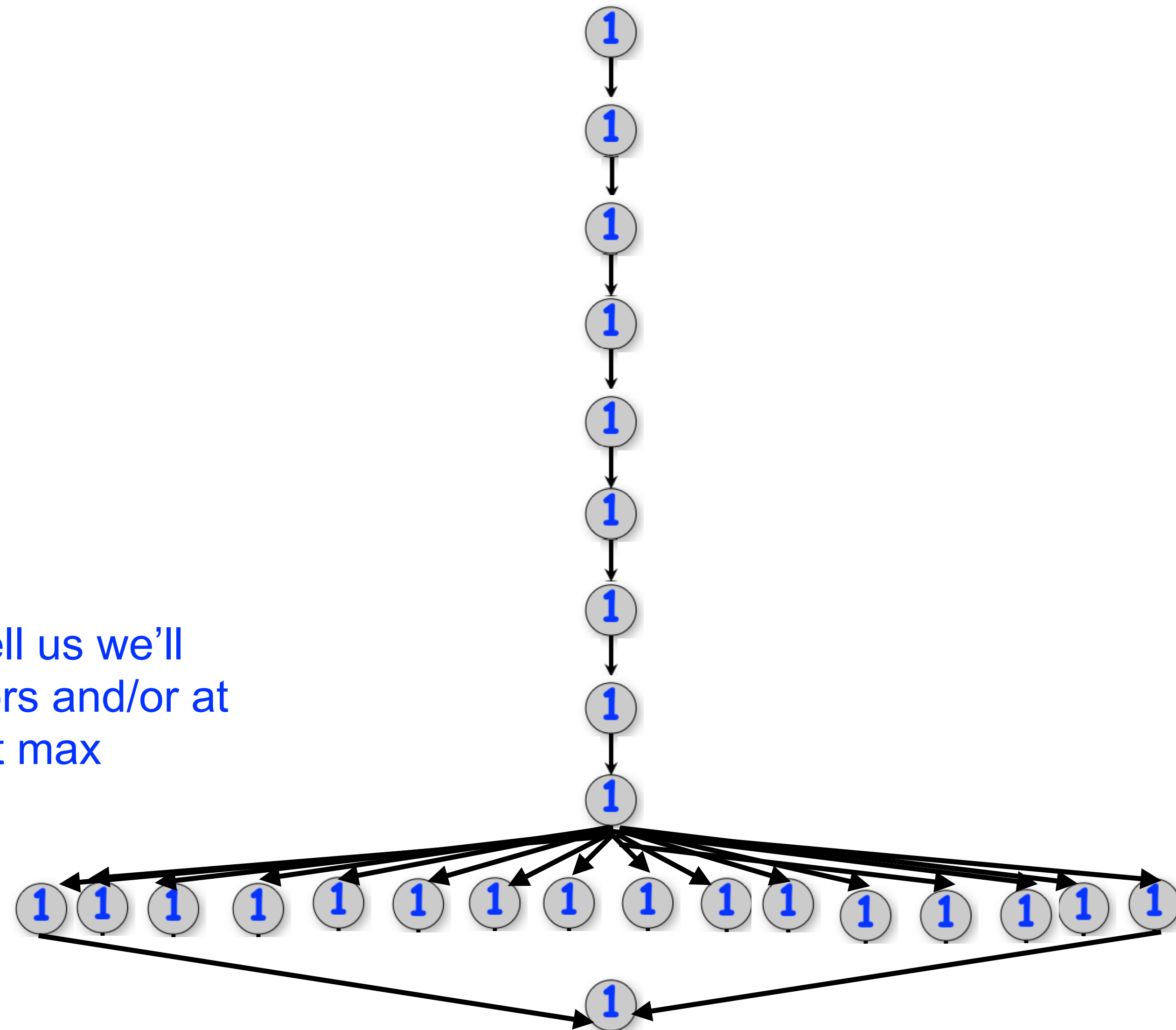
Example:

$$WORK(G) = 26$$

$$CPL(G) = 11$$

$$\text{Ideal Parallelism} = WORK(G)/CPL(G) = 26/11 \sim 2.36$$

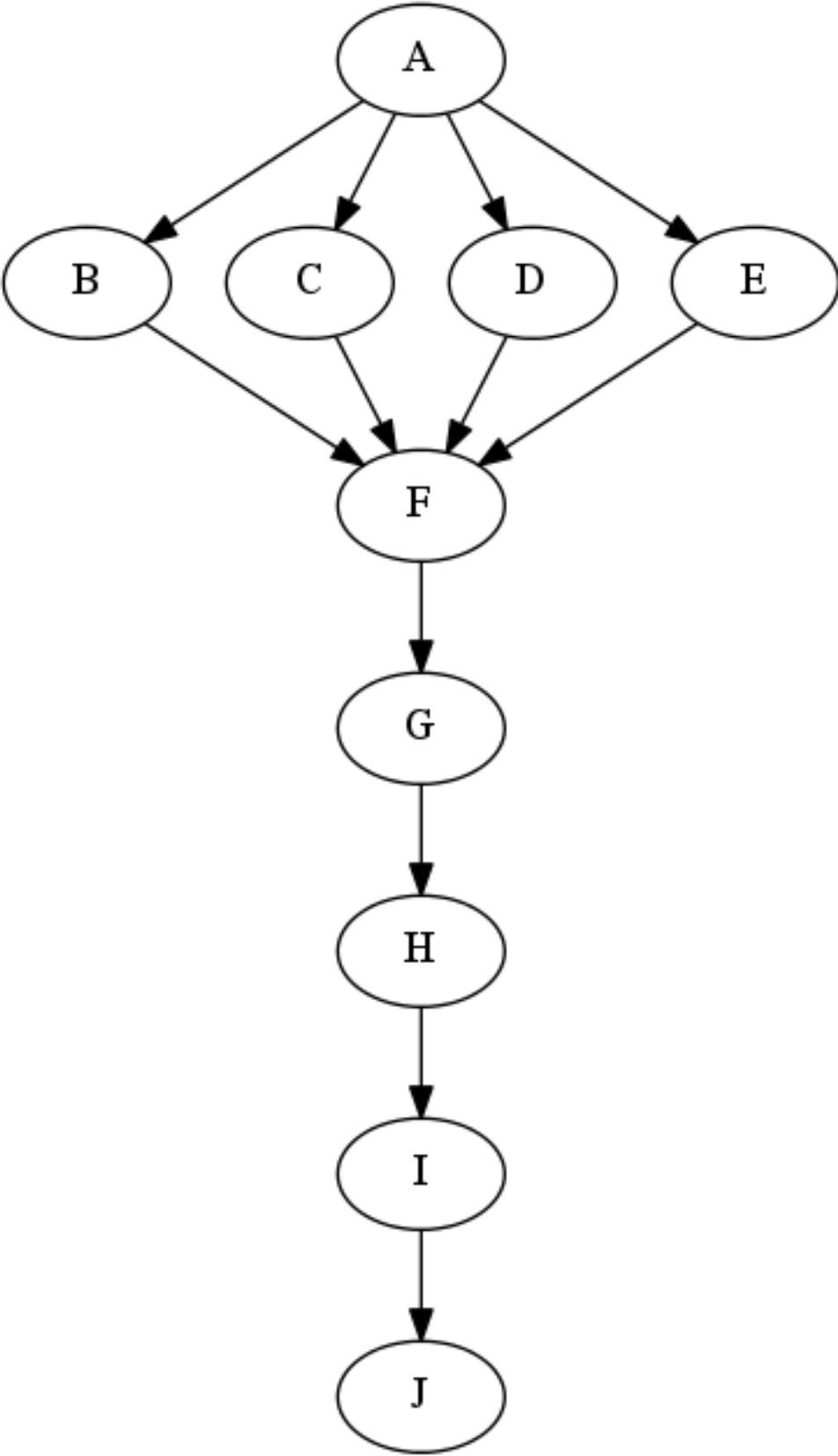
Does ideal parallelism tell us we'll need at least x processors and/or at most y processors to get max speedup?



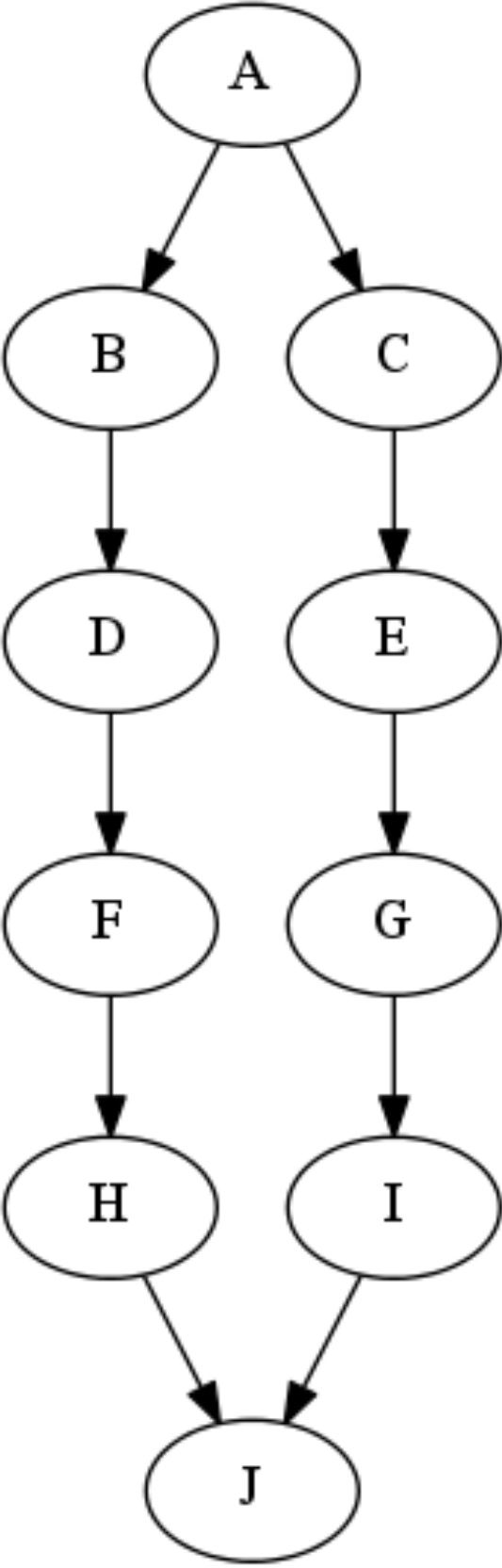
Which Computation Graph has more ideal parallelism?

Assume that all nodes have TIME = 1, so WORK = 10 for both graphs.

Computation Graph 1



Computation Graph 2



Announcements & Reminders

- IMPORTANT:
 - [Watch videos](#) for topics 1.1, 4.5 for next lecture
- HW 1 is due on Friday, Feb 4th
- Quiz 2 is due on Sunday, Feb 6th
- Worksheets due same day by 11:59pm for full credit, before next class for partial credit (0.5)
- Module 1 handout is available
- See course web site for syllabus, work assignments, due dates, ...
 - <http://comp322.rice.edu>

